

Approximations of Kinetic Equations

Peter Kauf, Manuel Torrilhon

ETH Zurich, Seminar for Applied Mathematics

Disentis

17-19 Aug 2009

ProDoc Klausur



1 Kinetic Theory

2 Closures

3 16 Velocities

4 Generalization

5 Hybrid Approach

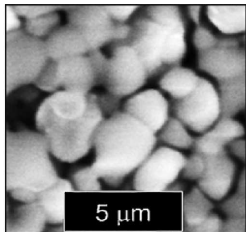
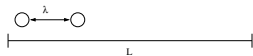
6 Summary

Modelling Beyond Equilibrium ...

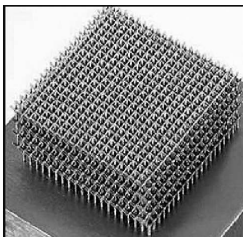
- ▶ Particle **collisions** drive system into **equilibrium**
→ equilibrium thermodynamics.
- ▶ Small scales → **few** collisions
→ extended, **non-equilibrium** thermodynamics

Scaling Parameter:

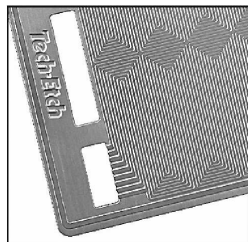
$$\text{Knudsen Number } \varepsilon = \frac{\text{mean free path} \equiv \lambda}{\text{system size} \equiv L}$$



porous media



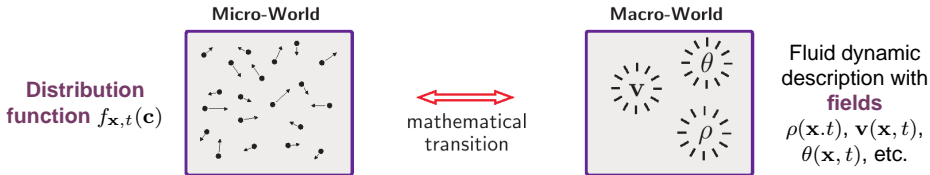
micro heat exchanger



micro fuel cell

Kinetic Theory

- ◆ provides a general modeling framework for multi-scale **micro-macro** transitions:

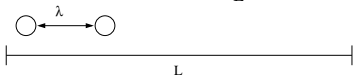


- ◆ **Microscopic:**

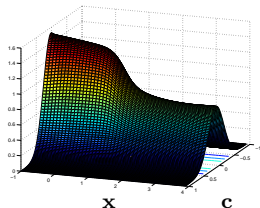
$$\underbrace{\partial_t f_{\mathbf{x},t}(\mathbf{c}) + c_k \partial_{x_k} f_{\mathbf{x},t}(\mathbf{c})}_{\text{advection}} = \underbrace{\frac{1}{\varepsilon} J(f, f)}_{\text{collisions}} \stackrel{\text{scale}}{=} \text{linearized} = -\frac{1}{\varepsilon} K f \quad \text{BOLTZMANN (1872)}$$

- ★ $f_{\mathbf{x},t}(\mathbf{c})d\mathbf{c}$ = gives **number density** of particles in $[\mathbf{c}, \mathbf{c} + d\mathbf{c}]$.

- ★ **Knudsen Number** $\varepsilon = \frac{\lambda}{L}$

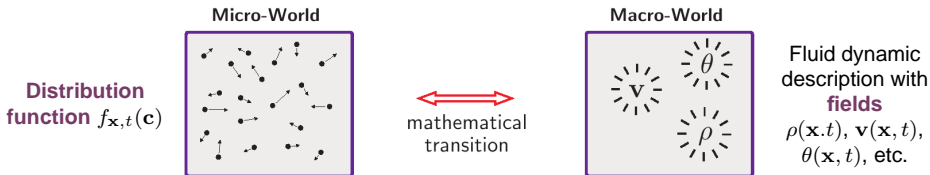


1+1 dimensional example: $f_{\mathbf{x},t_0}(\mathbf{c})$



Kinetic Theory

- ◆ provides a general modeling framework for multi-scale **micro-macro** transitions:



- ◆ **Macroscopic: (moment equations)**

$$\rho(\mathbf{x},t) = m \int_{\mathbb{R}^3} f d\mathbf{c}, \quad F_{i_1 \dots i_n}(t, \mathbf{x}) = m \int_{\mathbb{R}^3} c_{i_1} \dots c_{i_n} f_{\mathbf{x},t}(\mathbf{c}) d\mathbf{c}$$

Complexity reduction $f_{\mathbf{x},t}(\mathbf{c})$, $\mathbf{c} \in \mathbb{R}^3 \longleftrightarrow \{F_{i_1 \dots i_n}(\mathbf{x},t)\}_{n=0,1,\dots,N}$.

Corresponds to special spectral method with monomials $c_{i_1} \dots c_{i_n}$ as test functions.

$$\left. \begin{aligned} \partial_t F + \partial_i F_i &= 0 \\ \partial_t F_i + \partial_j F_{ij} &= 0 \\ \partial_t F_{kk} + \partial_i F_{ikk} &= 0 \end{aligned} \right\} \text{cons. laws}$$

$$\begin{aligned} \partial_t F_{\langle ij \rangle} + \partial_k F_{\langle ij \rangle k} &= P_{ij} \\ \partial_t F_{ijk} + \partial_l F_{ijkl} &= P_{ijk} \\ \vdots & \quad \ddots \end{aligned}$$

Fluid Variables:

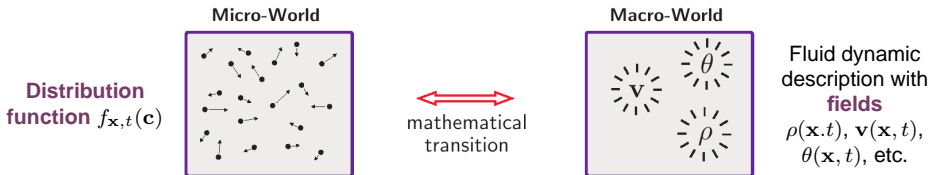
$$F = \rho, F_i = \rho v_i, F_{kk} = 3\rho\theta + \rho v_k^2, \\ F_{\langle ij \rangle} \sim \sigma_{ij}, F_{ikk} \sim q_i$$

Hierarchical Structure:

$$\text{Flux}(N) \equiv \text{variable}(N+1): \\ \longrightarrow \text{Closure Problem.}$$

Kinetic Theory

- ◆ provides a general modeling framework for multi-scale **micro-macro** transitions:



- ◆ **Transition: Modelling**

$$F_{i_1 \dots i_N k} \approx \int_{\mathbb{R}^3} c_{i_1} \dots c_{i_N} c_k \mathbf{f}^{(\text{model})}(\lambda_\alpha[\mathbf{F}, \mathbf{F}_i, \dots, \mathbf{F}_{i_1 \dots i_N}](\mathbf{x}, t), \mathbf{c}) d\mathbf{c}, \quad \alpha = 1, \dots, N,$$

λ_α any functional acting on $F_{i_1 \dots i_n}(\cdot, \cdot)$.

Goal: Find $f^{(\text{model})}$ such that resulting system

$$\partial_t U + \text{div } \mathcal{F}(U) = \mathcal{P}(U)$$

- ◆ has nice mathematical properties (stability),
- ◆ and is physically accurate.

Low dimensional approximation of high dimensional problem.

Linearized Boltzmann

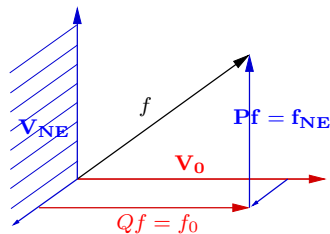
$$\partial_t f + \mathbf{c} \cdot \nabla f + \frac{1}{\varepsilon} K f = 0, \quad f_{\mathbf{x}, t}(\cdot) \in V, \quad \text{Equilibrium: } \{f : K f = 0\} = \ker(K) := V_0 \subset V.$$

Parametrization of Equilibrium

moments	$M : \mathbb{R}^m \ni \rho$	$\xrightarrow{\text{surjective}}$	$f_0 \in \ker K \equiv V_0$	distribution
distribution	$E_0 : V \ni f$	$\xrightarrow{\text{surjective}}$	$\rho \in \mathbb{R}^m$	moments

Features:

- ▶ $E_0 M = id_{\mathbb{R}^m \rightarrow \mathbb{R}^m}$.
- ▶ $V_{NE} := V \setminus V_0$: non-equilibrium phase space.
- ▶ $Q := M E_0 = id_{V_0} + 0_{V_{NE}} : V \rightarrow V_0$ (surjective)
"equilibrium projection".
- ▶ $P := id - Q = id_{V_{NE}} + 0_{V_0} : V \rightarrow V_{NE}$ (surjective)
"non-equilibrium projection".



Classical Closures

$$\partial_t f + c \partial_x f = -\frac{1}{\varepsilon} K f$$

◆ Chapman-Enskog (1916) expansion in Knudsen number ε :

Ansatz :

$$f = M\rho + \varepsilon f_1 + \varepsilon^2 f_2 + \mathcal{O}(\varepsilon^3).$$

Euler / Navier-Stokes-Fourier equations

$$\partial_t \rho + E_0 \mathbf{c} \cdot \nabla M\rho = 0 + \varepsilon E_0 (\mathbf{c} \cdot \nabla) K^\dagger (\mathbf{c} \cdot \nabla) M\rho$$

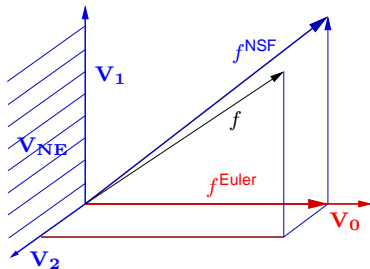
0^{th} order $\rightarrow f_1 = 0$ (Euler Equations)

1^{st} order $\rightarrow f_1 = -K^\dagger \mathbf{c} \cdot \nabla M\rho$ (NSF)

2^{nd} order \rightarrow Burnett Equations

⊖ 2^{nd} order unstable

⊕ accurate



Classical Closures

$$\partial_t f + c \partial_x f = -\frac{1}{\varepsilon} K f$$

- ◆ Chapman-Enskog (1916) expansion in Knudsen number ε :

Ansatz :

$$f = M\rho + \varepsilon f_1 + \varepsilon^2 f_2 + \mathcal{O}(\varepsilon^3).$$

Euler / Navier-Stokes-Fourier equations

$$\partial_t \rho + E_0 \mathbf{c} \cdot \nabla M\rho = 0 + \varepsilon E_0 (\mathbf{c} \cdot \nabla) K^\dagger (\mathbf{c} \cdot \nabla) M\rho$$

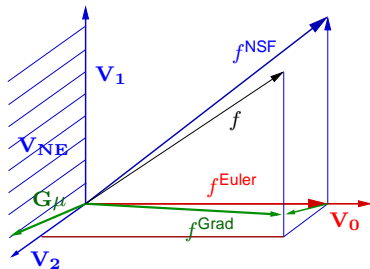
0th order $\rightarrow f_1 = 0$ (Euler Equations)

1st order $\rightarrow f_1 = -K^\dagger \mathbf{c} \cdot \nabla M\rho$ (NSF)

2nd order \rightarrow Burnett Equations

⊖ 2nd order unstable

⊕ accurate



- ◆ Grad: assume $f = M\rho + G\mu$. $\mu \in W \subset \mathbb{R}^s$, $G: \mathbb{R}^s \rightarrow V_{NE}$ arbitrary direction.

Grad's equations (1949)

$$\partial_t \rho + E_0 \mathbf{c} \cdot \nabla M\rho + E_0 \mathbf{c} \cdot \nabla G\mu = 0$$

$$\partial_t \mu + E_1 \mathbf{c} \cdot \nabla M\rho + E_1 \mathbf{c} \cdot \nabla G\mu + \frac{1}{\varepsilon} E_1 K G\mu = 0$$

⊕ stable

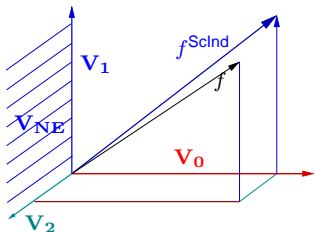
⊖ accuracy unclear

Scale Induced Closure [Torrilhon, Kauf, Levermore, Junk 2008; Struchtrup 2004]

Idea:

Combine **stability** of Grad and **accuracy** of Chapman-Enskog: $f = M\rho + \varepsilon G\mu + \varepsilon^2 f_2$.

Separation of phase space into $V = V_0 \oplus V_{NE} = \underbrace{V_0}_{\text{equilibrium}} \oplus \underbrace{V_1^\varepsilon}_{\text{1st order NE}} \oplus \underbrace{V_2^{\varepsilon^2}}_{\text{2nd order NE}} \oplus \dots$ higher NE



From kinetic equation: $G = -K^\dagger \mathbf{c} M D^\dagger$,
 $D^\dagger : \mu \mapsto \nabla \rho$

Equations

$$\partial_t \rho + E_0 \mathbf{c} \cdot \nabla M \rho - E_0 \mathbf{c} \cdot \nabla G \mu = 0$$

$$\partial_t \mu + E_1 \mathbf{c} \cdot \nabla M \rho - E_1 \mathbf{c} \cdot \nabla G \mu - \frac{1}{\varepsilon} E_1 K G \mu = 0$$

\oplus stable

\oplus accurate to 2nd order.

Scale Induced Closure

From kinetic equation: $G = -K^\dagger \mathbf{c} M D^\dagger$, $D^\dagger : \mu \mapsto \nabla \rho$

Equations

$$\begin{aligned} \partial_t \rho + E_0 \mathbf{c} \cdot \nabla M \rho - E_0 \mathbf{c} \cdot \nabla G \mu &= 0 \\ \partial_t \mu + E_1 \mathbf{c} \cdot \nabla M \rho - E_1 \mathbf{c} \cdot \nabla G \mu - \frac{1}{\varepsilon} E_1 K G \mu &= 0 \end{aligned} \quad (1)$$

- ◆ **Theorem 1:** [Torrilhon, Kauf, Levermore, Junk 2008/2009]
Under moderate conditions, the equations (1) are of 2nd order if expanded in ε .
→ **Generalization of Chapman-Enskog**
- ◆ **Theorem 2:** [Torrilhon, Kauf, Levermore, Junk 2008/2009]
If K symmetric and positive semi definite, (1) features a convex entropy with associated negative definite entropy production.
→ **stability**

⊕ stable

⊕ accurate to 2nd order.

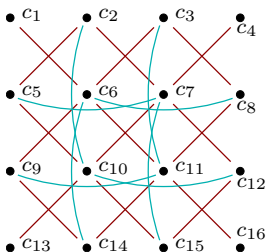
Generalizations to **higher orders** possible.

16 Discrete Velocity Model

[Babovsky, Kauf 2008]

Goal: Analyse abilities of different closures in simplified (1+1+2 dim) collision model.

Discrete velocity space:



Linearization and Fourier transform (in x):

$$\partial_t \hat{f}_j^k(t) - i \sum_{j=1}^{16} V_{ijk} \hat{f}_j^k(t) + \frac{1}{\varepsilon} \sum_{j=1}^{16} K_{ij} \hat{f}_j^k(t) = 0,$$

exact Solution: $\hat{\mathbf{f}}^k(t) = \exp \left[\underbrace{ik\mathbf{V}}_{\text{transport} \equiv \text{oscillation}} \underbrace{-\frac{1}{\varepsilon}\mathbf{K}}_{\text{interaction} \equiv \text{damping}} \right] \hat{\mathbf{f}}^k(0)$

Features of K :

▶ $\dim(\ker(K)) = 4$

▶ $\dim(V_1) = 3$

▶ $\dim(V_2) = 9$

Low dimensional multiscale approximation of high dimensional problem.

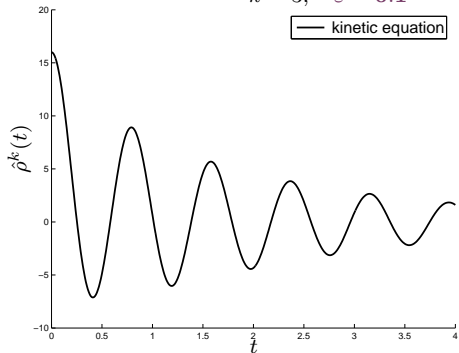
4/16 (Euler, NSF)

7/16 (Grad, Scale Induced Closure)

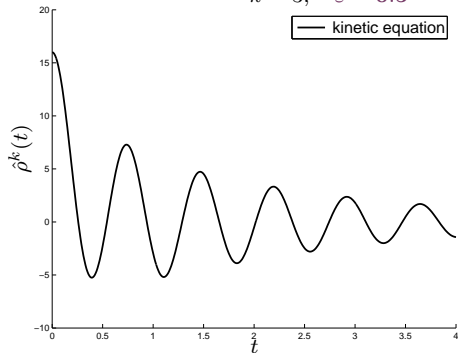
Comparison of Results

$$\hat{\rho}^k(t) = \sum_{j=1}^{16} \hat{f}_j^k(t)$$

$k = 3, \quad \varepsilon = 0.1$



$k = 3, \quad \varepsilon = 0.5$



transport \equiv oscillation

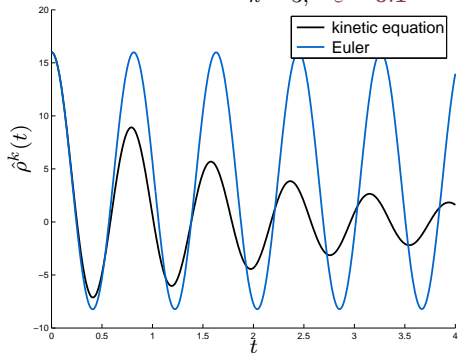
exact Solution: $\hat{\mathbf{f}}^k(t) = \exp\left[\underbrace{ik\mathbf{V}}_{\text{transport}} \underbrace{-\frac{1}{\varepsilon}\mathbf{K}}_{\text{interaction}} \right] \hat{\mathbf{f}}^k(0)$

interaction \equiv damping

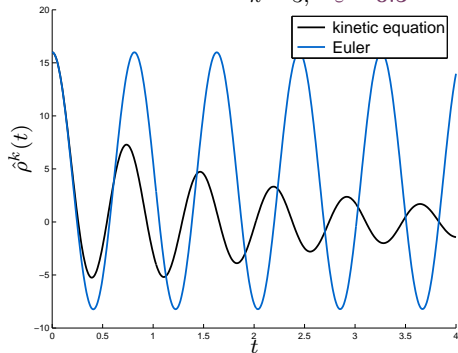
Comparison of Results

$$\hat{\rho}^k(t) = \sum_{j=1}^{16} \hat{f}_j^k(t)$$

$k = 3, \quad \varepsilon = 0.1$



$k = 3, \quad \varepsilon = 0.5$



transport \equiv oscillation

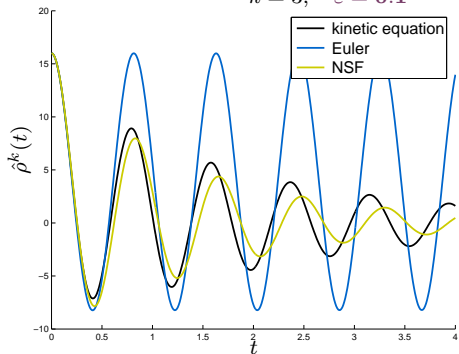
exact Solution: $\hat{\mathbf{f}}^k(t) = \exp\left[\underbrace{ik\mathbf{V}}_{\text{transport}} \underbrace{-\frac{1}{\varepsilon}\mathbf{K}}_{\text{interaction}} \right] \hat{\mathbf{f}}^k(0)$

interaction \equiv damping

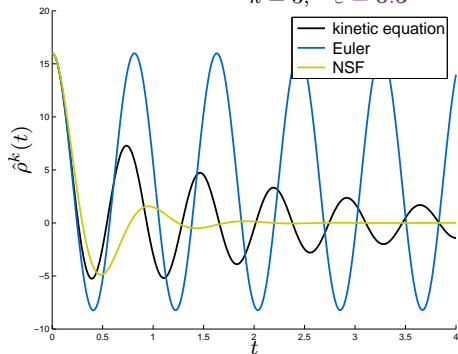
Comparison of Results

$$\hat{\rho}^k(t) = \sum_{j=1}^{16} \hat{f}_j^k(t)$$

$k = 3, \quad \varepsilon = 0.1$



$k = 3, \quad \varepsilon = 0.5$



transport \equiv oscillation

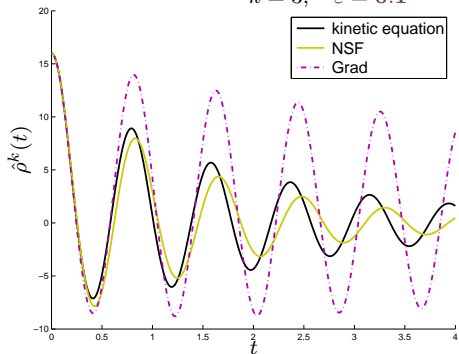
exact Solution: $\hat{\mathbf{f}}^k(t) = \exp\left[\underbrace{ik\mathbf{V}}_{\text{transport}} \underbrace{-\frac{1}{\varepsilon}\mathbf{K}}_{\text{interaction}} \right] \hat{\mathbf{f}}^k(0)$

interaction \equiv damping

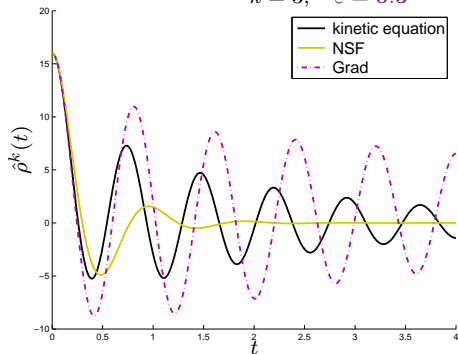
Comparison of Results

$$\hat{\rho}^k(t) = \sum_{j=1}^{16} \hat{f}_j^k(t)$$

$k = 3, \quad \varepsilon = 0.1$



$k = 3, \quad \varepsilon = 0.5$



transport \equiv oscillation

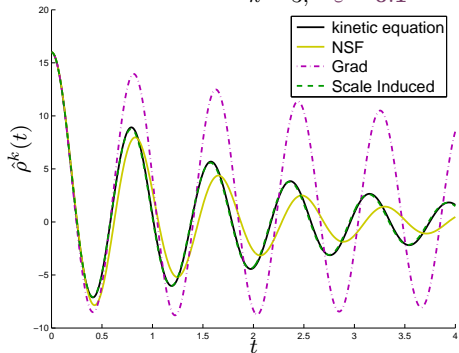
exact Solution: $\hat{\mathbf{f}}^k(t) = \exp\left[\underbrace{ik\mathbf{V}}_{\text{transport}} \underbrace{-\frac{1}{\varepsilon}\mathbf{K}}_{\text{interaction}} \right] \hat{\mathbf{f}}^k(0)$

interaction \equiv damping

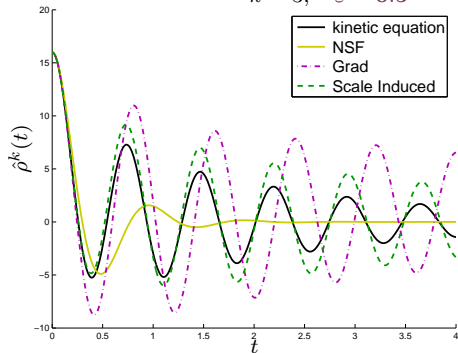
Comparison of Results

$$\hat{\rho}^k(t) = \sum_{j=1}^{16} \hat{f}_j^k(t)$$

$k = 3, \quad \varepsilon = 0.1$



$k = 3, \quad \varepsilon = 0.5$



transport \equiv oscillation

exact Solution: $\hat{\mathbf{f}}^k(t) = \exp\left[\underbrace{ik\mathbf{V}}_{\text{transport}} \underbrace{-\frac{1}{\varepsilon}\mathbf{K}}_{\text{interaction}} \right] \hat{\mathbf{f}}^k(0)$

interaction \equiv damping

Beyond Kinetic Theory

Example from Kinetic Theory shows **more general abilities** of Scale Induced Closure:

$$N \gg 1$$

$$y'(t) = Ay - \frac{1}{\varepsilon}By, \quad y \in \mathbb{R}^N, \quad B \text{ sym. pos. semidef.}$$

- ▶ Parametrize (low dimensional) $\ker B$ by ρ, M .
- ▶ Choose accuracy of order C $y = M\rho + \varepsilon G_1^{A,B} \mu_1^{A,B} + \dots + \varepsilon^C G_C^{A,B} \mu_C^{A,B}$
- ▶ **Order of Magnitude** determines higher moments $\mu_i^{A,B}, G_i^{A,B}$ out of A and B , $i = 1, \dots, C$.
- ▶ Solve low dimensional system for $\rho, \mu_1^{A,B}, \dots, \mu_C^{A,B}$

General approximation theory **without spectral gap** but with **cascade of scales** induced by $1, \varepsilon, \dots, \varepsilon^C$.

Any Examples ?

Summary

- ◆ Kinetic Equation: high dimensional, many details
 - ◆ Classical Closures:
 - * Chapman-Enskog: $f = M\rho + \varepsilon f_1 + \varepsilon^2 f_2 + \mathcal{O}(\varepsilon^3)$; equilibrium variables used.
 ⊕ accurate, ⊖ higher orders unstable.
 - * Grad: $f = M\rho + G\mu$; arbitrary direction in phase space.
 ⊖ unclear accuracy, ⊕ stable.
 - ◆ Scale Induced Closure: $f = M\rho + \varepsilon G\mu + \mathcal{O}(\varepsilon^2)$,
 kinetic equation $\rightarrow G = -K^\dagger c M D^\dagger$
 ⊕ accurate, ⊕ stable.
- ▶ Provides equations in **transition regime** of kinetic theory.
 - ▶ Can be used for **low dimensional approximations** of **general stiff problems**.

Hybrid Approach: Ideas

$$\underbrace{\partial_t f_{\mathbf{x},t}(\mathbf{c}) + c_k \partial_{x_k} f_{\mathbf{x},t}(\mathbf{c})}_{\text{advection}} = \underbrace{\frac{1}{\varepsilon} J(f, f)}_{\text{collisions}} \stackrel{\text{scale}}{=} \text{BGK} - \frac{1}{\varepsilon} \left(\frac{\rho}{\sqrt{2\pi\theta}} \exp\left(\frac{(c-v)^2}{2\theta}\right) - f \right)$$

Problems:

- ▶ $f(\mathbf{x}, t, \mathbf{c})$ expensive ($\mathbf{c} \in \mathbb{R}^3$)
- ▶ Too many details in most situations
- ▶ Non-Galilei invariant formulation (moving mesh)

Ideas:

- ▶ Use weak formulation, transform to Galilei-invariant form.
- ▶ Approximate $f_{\mathbf{x},t}(\mathbf{c})$ appropriately (moments, point values, Gaussians,...)
- ▶ Couple to conservation laws to guarantee conservation of ρ, v, θ .

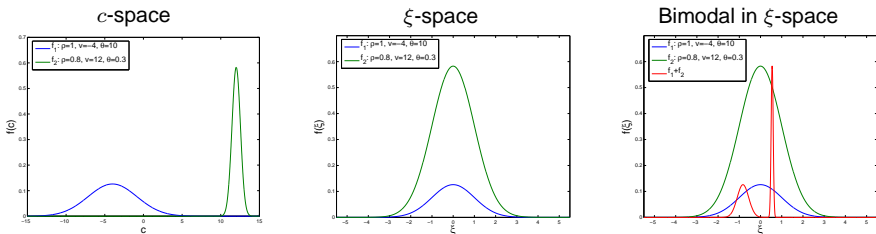
Galilei Invariant, Scaled Formulation

Transfer Equation (Boltzmann equation in weak form):

$$(\rho\langle\psi\rangle)_t + (\rho\langle c_k\psi\rangle)_{x_k} = m \int f \partial_t \psi dc + m \int f c_k \partial_{x_k} \psi dc + m \int \psi S(f, f) dc$$

Moving Mesh:

Rescale c_i to $\xi_i = \frac{c_i - v_i(\mathbf{x}, t)}{\sqrt{\theta(\mathbf{x}, t)}}$, writing $f(t, x, c) = \hat{f}(t, x, \xi)$.



Galilei invariant! Domain **centered around zero**. No reduction in resolution.

Note: Cannot get full f from \hat{f} (unknown v, θ).

Linking constraints: $\int \xi \hat{f} d\xi = 0$, $\int \hat{f} d\xi = \frac{\rho}{\sqrt{\theta}^d}$, $\frac{1}{d} \int \xi^2 \hat{f} d\xi = \frac{\rho}{\sqrt{\theta}^d}$

Decomposition of \hat{f}

Moment Equations (no c) \longleftarrow ????? \longrightarrow pointwise discretization of c

Moments offer highly **efficient** discretizations close to **equilibrium**, while **point values** capture **small scale** behaviour.

How to **combine**?

Decompose:

$$\hat{f}(t, x, \xi) = \sum_{\beta=1}^N \kappa_{\beta}(x, t) \hat{\phi}_{\beta}(\xi)$$

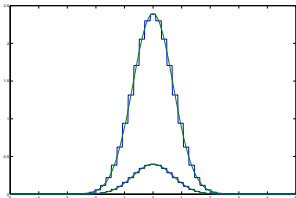
$\hat{\phi}_{\alpha}(\xi)$ **Basisfunctions**

$\kappa_{\beta}(t, x)$ **coefficients.**

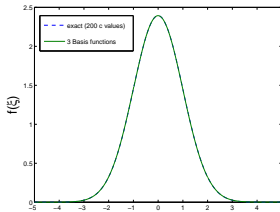
$\langle f, g \rangle := \int f g d\xi$ and $M^{\alpha\beta} = \langle \hat{\phi}_{\alpha}, \hat{\phi}_{\beta} \rangle$.

$$\implies \kappa_{\beta}(t, x) = \sum_{\alpha=1}^N (M^{-1})_{\alpha\beta} \int \hat{f} \hat{\phi}_{\alpha} d\xi$$

$\hat{\phi}$ Piecewise Constants



$\hat{\phi}$ Gaussian



Transfer Equation for $\kappa_\alpha(t, x)$

Rewrite transfer equation, testing with $\hat{\psi}(t, x, \xi) = \frac{1}{\rho(t, x)} \hat{\phi}(\xi)$:

$$(\rho\langle\psi\rangle)_t + (\rho\langle c_k\psi\rangle)_{x_k} = m \int f \partial_t \psi dc + m \int f c_k \partial_{x_k} \psi dc + m \int \psi S(f, f) dc$$

↓ ↓ ↓ ↓ ↓ ↓ 'material equations'

$$\begin{aligned}
 M^{\alpha\beta} \partial_t \kappa_\beta + \left[M^{\alpha\beta} v_k + M_k^{\alpha\beta} \sqrt{\theta} \right] \partial_{x_k} \kappa_\beta &= \quad \left. \vphantom{M^{\alpha\beta}} \right\} \text{advec.} \\
 + \left[\left(G_{s,s}^{\alpha\beta} \partial_t + \left(G_{s,s}^{\alpha\beta} v_k + G_{ks,s}^{\alpha\beta} \sqrt{\theta} \right) \partial_{x_k} \right) \ln(\theta^{1/2}) \right. & \left. \vphantom{G_{s,s}^{\alpha\beta}} \right\} \text{relax.} \\
 + \frac{1}{\sqrt{\theta}} \left(G_{,j}^{\alpha\beta} \partial_t + \left(G_{,j}^{\alpha\beta} v_k + \sqrt{\theta} G_{k,j}^{\alpha\beta} \right) \partial_{x_k} \right) v_j - \frac{1}{\tau} M^{\alpha\beta} \kappa_\beta(x, t) & \\
 + \frac{1}{\tau} \frac{\rho}{(2\pi\theta)^{d/2}} \int \hat{\phi}_\alpha(\xi) e^{-\xi_k^2} d\xi & \left. \vphantom{\frac{1}{\tau}} \right\} \text{source}
 \end{aligned}$$

$$M_k^{\alpha\beta} = \int \xi_k \hat{\phi}_\alpha \hat{\phi}_\beta d\xi, \quad G_{,j}^{\alpha\beta} = \int \hat{\phi}_\alpha \partial_{\xi_j} \hat{\phi}_\beta d\xi, \quad G_{k,j}^{\alpha\beta} = \int \xi_k \hat{\phi}_\alpha \partial_{\xi_j} \hat{\phi}_\beta d\xi,$$

$$G_{kj,j}^{\alpha\beta} = \int \xi_k \xi_j \hat{\phi}_\alpha \partial_{\xi_j} \hat{\phi}_\beta d\xi \quad \text{all pure numbers (indep. of } t, x, \xi)$$

Coupling through Heat Flux

Main idea:

Solve **closure problem for q** in conservation laws by **coupling** to material equations:

$$\begin{aligned}
 q_k &= m \int (c_k - v_k)(c_l - v_l)^2 f dc = \sqrt{\theta}^{d+3} \int \xi^2 \xi_k \hat{f} d\xi \\
 &\cong m \sqrt{\theta}^{d+3} \sum_{\beta=1}^N \kappa_{\beta}(t, x) \int \xi^2 \xi_k \hat{\phi}_{\beta} d\xi := \sqrt{\theta}^{d+3} \sum_{\beta=1}^N \kappa_{\beta} V_{3;k}^{\beta}
 \end{aligned}$$

Features:

- ▶ Enable **macro-balance** through conservation laws.
- ▶ **Constraints couple** κ_{β} to macro-level.

Define further **pure numbers**:

$$V_0^{\alpha} := \int \hat{\phi}_{\alpha}(\xi) d\xi$$

$$V_{1;i}^{\alpha} := \int \xi_i \hat{\phi}_{\alpha}(\xi) d\xi$$

$$V_2^{\alpha} := \int \xi_k \xi_k \hat{\phi}_{\alpha}(\xi) d\xi$$

$$V_{\text{exp}}^{\alpha} := \int \hat{\phi}_{\alpha}(\xi) e^{-\xi_k^2} d\xi$$

Boltzmann \cup Conservation Laws

Coupled equations in 1+1 dimensions

$$\left. \begin{aligned} \partial_t \rho + \partial_x(\rho v) &= 0 \\ \partial_t(\rho v) + \partial_x(\rho v^2 + \rho \theta) &= 0 \\ \partial_t \left(\frac{1}{2} \rho \theta + \frac{1}{2} \rho v^2 \right) + \partial_x \left[\left(\frac{1}{2} \rho \theta + \frac{1}{2} \rho v^2 \right) v + \rho \theta v + q \right] &= 0 \end{aligned} \right\} \text{cons. laws}$$

$$\mathbf{q} = m \theta^2 \kappa_{\beta}(\mathbf{x}, t) \mathbf{V}_{3;\mathbf{k}}^{\beta} \left. \vphantom{\mathbf{q}} \right\} \text{coupling}$$

$$\left. \begin{aligned} M^{\alpha\beta} \partial_t \kappa_{\beta} + \left[M^{\alpha\beta} v_k + M_k^{\alpha\beta} \sqrt{\theta} \right] \partial_{x_k} \kappa_{\beta} &= \\ + \left[\left(G_{s,s}^{\alpha\beta} \partial_t + \left(G_{s,s}^{\alpha\beta} v_k + G_{ks,s}^{\alpha\beta} \sqrt{\theta} \right) \partial_{x_k} \right) \ln(\theta^{1/2}) \right. \\ + \frac{1}{\sqrt{\theta}} \left(G_{,j}^{\alpha\beta} \partial_t + \left(G_{,j}^{\alpha\beta} v_k + \sqrt{\theta} G_{k,j}^{\alpha\beta} \right) \partial_{x_k} \right) v_j - \frac{1}{\tau} M^{\alpha\beta} \left. \right] \kappa_{\beta}(x, t) &= \\ + \frac{1}{\tau} \frac{\rho}{(2\pi\theta)^{d/2}} \int \hat{\phi}_{\alpha}(\xi) e^{-\xi_k^2} d\xi & \end{aligned} \right\} \text{mat. equations}$$

$$\left. \kappa_{\beta}(x, t) V_0^{\beta} \stackrel{!}{=} \kappa_{\beta}(x, t) V_2^{\beta}, \quad \kappa_{\beta}(x, t) V_{1;i}^{\beta} \stackrel{!}{=} 0 \right\} \text{constraints}$$

Remarks:

- ▶ Use sum convention.
- ▶ Matrices M , G , vectors V , are **known pure numbers**.
- ▶ **Hyperbolicity?**, accuracy?
- ▶ **Constraints?**

Conclusions

- ◆ Scale Induced Closure: $f = M\rho + \varepsilon G\mu + \mathcal{O}(\varepsilon^2)$,
kinetic equation $\longrightarrow G = -K^\dagger c M D^\dagger \quad \oplus$ accurate, \oplus stable.

- ▶ Provides equations in **transition regime** of kinetic theory.
- ▶ Can be used for **low dimensional approximations** of **general stiff problems**.

- ◆ Kinetic Equation: High detail resolution in all (kinetic) regimes.

- ▶ **Galilei-invariant, scaled weak formulation.**
- ▶ **General Decomposition** $\hat{f} = \sum_{\beta=1}^N \kappa_\beta(x, t) \hat{\phi}_\beta(\xi)$
- ▶ **Coupling** of Boltzmann and Conservation Laws through heat flux q .
- ▶ **Hyperbolicity? Accuracy?**

Conclusions

- ◆ Scale Induced Closure: $f = M\rho + \varepsilon G\mu + \mathcal{O}(\varepsilon^2)$,
kinetic equation $\rightarrow G = -K^\dagger c M D^\dagger$ \oplus accurate, \oplus stable.

- ▶ Provides equations in **transition regime** of kinetic theory.
- ▶ Can be used for **low dimensional approximations** of **general stiff problems**.

- ◆ Kinetic Equation: High detail resolution in all (kinetic) regimes.

- ▶ **Galilei-invariant, scaled weak formulation.**
- ▶ **General Decomposition** $\hat{f} = \sum_{\beta=1}^N \kappa_\beta(x, t) \hat{\phi}_\beta(\xi)$
- ▶ **Coupling** of Boltzmann and Conservation Laws through heat flux q .
- ▶ **Hyperbolicity? Accuracy?**

Engraziel fetg per Vossa atenziun !