**PRO\*DOC WORKSHOP** 

## Approximation by waves

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Homogeneous Helmholtz equation with impedance boundary conditions:

$$\begin{cases} -\Delta u - \omega^2 u = 0 & \text{in } \Omega, \\ \nabla u \cdot \mathbf{n} + i\omega u = g & \text{on } \partial\Omega, \end{cases}$$

 $\Omega \subset \mathbb{R}^N$ , N = 2, 3, bounded polyhedral domain,  $g \in L^2(\partial \Omega)$ , wavenumber  $\omega > 0$ .

With large  $\omega$ , standard finite elements are affected by the numerical dispersion and the pollution effect:

special FEM are required.

The Trefftz methods use basis functions that are solutions of the PDE under examination in each element.

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Homogeneous Helmholtz equation:  $-\Delta u - \omega^2 u = 0$ 

• plane wave basis functions (UWVF, PWDG, DEM, VTCR,...)

$$x\mapsto e^{i\omega d\cdot x}, \qquad |d|=1;$$

- circular / spherical / corner wave basis functions (least-squares Trefftz,...);
- singular / fundamental basis functions (MFS,...);

Ο...

The analysis of plane waves Trefftz methods requires best approximation estimates:

$$-\Delta u - \omega^2 u = 0$$
 in  $D$ , diam  $D = h$ ,  $p \in \mathbb{N}$ ,

$$\inf_{\alpha \in \mathbb{C}^p} \left\| u - \sum_{k=1}^p \alpha_k e^{i\omega d_k \cdot x} \right\|_{H^j(D)} \le C \epsilon(h, p) \| u \|_{H^{K+1}(D)},$$

with  $\epsilon(h,p) \xrightarrow[p \to \infty]{h \to 0} 0.$ 

Only few results are available (CESSENAT AND DESPRÉS 1998, MELENK 1995), improvement and generalization are needed.

#### Our goals:

- estimates for plane and circular/spherical waves;
- estimates both in h and p;
- estimates in 2 and 3 dimensions;
- explicit dependence of the bounds on  $\omega$ .

- Vekua theory;
- approximation by generalized harmonic polynomials;
- approximation by plane waves;
- approximation for Maxwell equations (only some ideas!).

## Part I

# Vekua theory

### The Vekua theory in N dimensions

 $D \subset \mathbb{R}^N, N \ge 2,$  star-shaped.

Given  $\omega > 0$ , define two continuous functions:

$$egin{aligned} M_1, M_2 &: D imes [0,1] o \mathbb{R} \ M_1(x,t) &= -rac{\omega |x|}{2} \; rac{\sqrt{t}^{N-2}}{\sqrt{1-t}} \, J_1(\omega |x| \sqrt{1-t}), \ M_2(x,t) &= -rac{i \omega |x|}{2} \; rac{\sqrt{t}^{N-3}}{\sqrt{1-t}} \, J_1(i \omega |x| \sqrt{t(1-t)}). \end{aligned}$$

 $J_1$  is the ordinary Bessel function of the first kind and order 1.

#### The Vekua operators

$$V_1,V_2:C(D)
ightarrow C(D),$$
 $V_j[\phi](m{x}):=\phi(m{x})+\int_0^1M_j(m{x},t)\phi(tm{x})\,\mathrm{d}t, \qquad m{a.e.}\ m{x}\in D,\ m{j}=1,2.$ 

#### The Vekua operators

$$V_1, V_2: C(D) o C(D),$$
 $V_j[\phi](x) := \phi(x) + \int_0^1 M_j(x,t) \phi(tx) \, \mathrm{d} t, \qquad a.e. \ x \in D, \ j=1,2.$ 

Short Vekua's story:

- Vekua 1942, Helmholtz equation in N dimensions, no proofs;
- Vekua 1948 (translated in 1967), elliptic equations in 2 dimensions, one page for N-dimensional Helmholtz;
- Henrici 1957, elliptic equations only in 2 dimensions.
- ightarrow *N*-dimensional version almost forgotten.

## The properties of Vekua operators

$$V_2 = (V_1)^{-1}$$

### The properties of Vekua operators

1 
$$V_2 = (V_1)^{-1}$$
  
2  $(-\Delta - \omega^2) u = 0 \iff \Delta V_2[u] = 0$ 

Main idea of Vekua theory:

Helmholtz solutions 
$$\xrightarrow{V_1}$$
 Harmonic functions

### The continuity of Vekua operators

Weighted Sobolev norms:

$$\| u \|_{j,\omega,D} := \left( \sum_{k=0}^{j} \omega^{2(j-k)} \, |u|_{k,D}^2 
ight)^{rac{1}{2}}, \qquad \omega > 0, \, j \in \mathbb{N}.$$

$$egin{aligned} &\Delta\phi = 0, \quad (-\Delta - \omega^2)u = 0; \ &\|V_1[\phi]\|_{j,\omega,D} &\leq C_1(N,j,
ho) \left(1 + (\omega h)^2
ight) \; \|\phi\|_{j,\omega,D} &j \geq 0 \;, \ &\|V_2[u]\|_{j,\omega,D} &\leq C_2(N,j,
ho) \left(1 + (\omega h)^4
ight) \; e^{rac{3}{4}\omega h} \; \|u\|_{j,\omega,D} &j \geq 1 \;, \ &N = 2,3, \quad u, \; \phi \in H^j(D). \end{aligned}$$

Key ingredients for the proof of the continuity of  $V_1$  and  $V_2$  are the interior estimates.

• For harmonic functions, these are well-known:

$$\Delta \phi = 0 \quad \Rightarrow \quad \left| \phi(x) 
ight|^2 \leq rac{1}{R^N \left| B_1 
ight|} \left\| \phi 
ight\|^2_{0, B_{(x,R)}}$$

• For Helmholtz solutions, N = 2, 3, we can prove estimates that are explicit in  $\omega$ :

## Part II

## Approximation by GHPs

## The approximation by GHPs

$$-\Delta u - \omega^2 u = 0,$$
  $u \in H^{k+1}(D),$ 

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### The approximation by GHPs

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#### $\downarrow V_1$

#### u can be approximated by

 $V_1 \begin{bmatrix} harmonic \\ polynomials \end{bmatrix} =: \begin{array}{c} \begin{array}{c} \text{generalized} \\ harmonic \\ polynomials \end{array}$  (GHPs).

## Generalized harmonic polynomials

In 2D, the GHPs are circular waves:

 $Q(x) = e^{il\psi} J_l(\omega r),$ 

in polar coordinates  $x=re^{i\psi}, \ l\in\mathbb{Z}$  ,

 $J_l = Bessel functions.$ 

In 3D, the GHPs are spherical waves:

 $Q(\mathbf{x}) = Y_{l,m}\left(\frac{\mathbf{x}}{|\mathbf{x}|}\right) \mathbf{j}_l(\omega|\mathbf{x}|),$ 

 $0\leq |m|\leq l\in\mathbb{N}$ ,

 $Y_{l,m}$  = spherical harmonics,  $j_l$  = spherical Bessel functions.

Both belong to the family of the Herglotz functions.

The GHPs are also called Fourier-Bessel functions.

#### Generalized harmonic polynomials

Real part of GHPs in  $[-1,1]^2$ :  $V_1[z^l]$ , l = 0, 2, 4,  $\omega = 10$ 



### The approximation by GHPs: *h*-convergence

$$\begin{split} \inf_{\substack{P \in \left\{ \begin{array}{l} \text{harmonic} \\ \text{polynomials} \\ \text{of degree } \leq L \end{array} \right\}} \|u - V_1[P]\|_{j,\omega,D} &\leq C \inf_{p} \|V_2[u] - P\|_{j,\omega,D} & \text{ contin. of } V_1, \\ &\leq C h^{k+1-j} \epsilon(L) \|V_2[u]\|_{k+1,\omega,D} & \text{ harmonic} \\ &\leq C h^{k+1-j} \epsilon(L) \|u\|_{k+1,\omega,D} & \text{ contin. of } V_2. \end{split}$$

For the *h*-convergence it is enough to use Bramble-Hilbert theorem: it provides a harmonic polynomial!

The constant C depends on  $\omega h$ , not on  $\omega$  alone:

$$C = C \cdot (1 + \omega h)^{j+6} e^{\frac{3}{4}\omega h}.$$

## Harmonic approximation: *p*-convergence, 2D

In 2 dimensions, if *D* satisfies the 'exterior cone condition', then:

$$\epsilon(L) = \left(\frac{\log(L+2)}{L+2}\right)^{\lambda(k+1-j)}$$

If D is convex,  $\lambda = 1$ . Otherwise  $\lambda = \min \frac{\text{re-entrant corner of } D}{\pi}$ .

Sharp *p*-estimate! (MELENK)

In 2D we can use complex analysis:

- conformal mappings  $B_1 \leftrightarrow D$ ;
- $\phi$  harmonic and real  $\rightarrow \phi = \text{Re}(\Phi \text{ holomorphic});$
- complex interpolation on  $B_1$ ;
- every (complex) polynomial is harmonic;

An analogous result holds in *N* dimensions:

$$\epsilon(L) = L^{-\lambda(k+1-j)},$$

where  $\lambda > 0$  is a geometric unknown parameter.

Follows from:

- an exponential approximation result for compact subsets by (BAGBY, BOS AND LEVENBERG 1996) in  $L^{\infty}$ -norm;
- harmonic dilation and deformation technique.

If u is the restriction of a solution in a larger domain (2 or 3D), the convergence in L is exponential.

## The approximation by GHPs: h&p-convergence

Harmonic polynomial approximation:

2-3D	h-conv.	harmonic Bramble-Hilbert: easy
2D	p-conv.	sharp estimate by Melenk: complex analysis
3D	p-conv.	new estimates, order of convergence not explicit

 $\downarrow$  Vekua continuity

If 
$$-\Delta u - \omega^2 u = 0$$
,  $N = 2, 3$ ,  $0 \le j \le k \le L$ 

 $\inf_{\substack{Q \in \left\{ \text{of degree } \leq L \right\}}} \left\| u - Q \right\|_{j,\omega,D} \leq C(\omega h) \ h^{k+1-j} \ L^{-\lambda(k+1-j)} \ \left\| u \right\|_{k+1,\omega,D},$ 

The rate  $\lambda > 0$  depends only on the shape of *D*. If it is convex and 2D, then  $\lambda = 1 - \varepsilon$ .

Best approx. estimate for spherical waves Trefftz methods!

## Part III

# Approximation by plane waves

Link between plane waves and circular/spherical waves: Jacobi-Anger expansion

$$\begin{array}{ll} \text{2D} & e^{iz\cos\theta} = \sum_{l\in\mathbb{Z}} i^l J_l(z) \; e^{il\theta}, & z\in\mathbb{C}, \; \theta\in\mathbb{R}, \\ \\ \text{3D} & \underbrace{e^{ir\xi\cdot\eta}}_{\text{plane wave}} = 4\pi \sum_{l\geq 0} \sum_{m=-l}^l i^l \underbrace{j_l(r) \; Y_{l,m}(\xi)}_{\text{GHP}} \overline{Y_{l,m}(\eta)}, & \xi, \; \eta\in S^2, \; r\geq 0. \end{array}$$

We need the other way round:

GHP = linear combination of plane waves

- ightarrow truncation of J-A expansion,
- $\rightarrow$  solution of a linear system,
- $\rightarrow$  residual estimates.

## The approximation of GHPs by plane waves: 2D

$$\begin{aligned} \mathsf{GHP} &- \sum_{k=-q}^{q} \alpha_{k} \; e^{i\omega x \cdot d_{k}} & (x = |x|e^{i\psi}, \; d_{k} = (\cos \theta_{k}, \sin \theta_{k}) \\ &= \sum_{\substack{l=-L \\ V[P], \; \text{degree } L \\ \end{array}}^{L} \alpha_{l} \; J_{l}(\omega|\mathbf{x}|) \; e^{il\psi} - \sum_{\substack{l \in \mathbb{Z} \\ l \in \mathbb{Z} \\ \end{array}} J_{l}(\omega|\mathbf{x}|) \; e^{il\psi} \; i^{l} \sum_{\substack{k=-q \\ \end{array}}^{q} \alpha_{k} \; e^{-il\theta_{k}} \\ &= -\sum_{\substack{|l| > q}} i^{l} \; J_{l}(\omega|\mathbf{x}|) \; e^{il\psi} \sum_{\substack{k=-q \\ k=-q}}^{q} \alpha_{k} \; e^{-il\theta_{k}}, \end{aligned}$$

where the vector  $\alpha_k$  is solution of a Vandermonde linear system:

 $\{e^{-il\theta_k}\}_{l,k}\cdot\alpha_k=i^{-l}a_l$ 

- bound on the inverse matrix;
- control on the minimal angular distance between plane waves directions (non equispaced case).

Given a harmonic polynomial P of degree at most  $L(\geq K)$ , there exists  $\alpha \in \mathbb{C}^{2q+1}$  such that

$$\left\| V_1[P] - \sum_{k=1}^{2q+1} \alpha_k \; e^{i\omega x \cdot d_k} \right\|_{L^{\infty}(B_{2h})} \leq C_{(\rho,L,\omega h)} \; h^{K-1} \; \left( \frac{c_0 \; (\omega h)^2}{q+1} \right)^{\frac{q+1}{2}} \|P\|_{K,\omega,D} \, .$$

The convergence is faster than exponential in q.

The constants C and  $c_0$  can be made completely explicit.

Cauchy estimates Vekua continuity  $\}$   $\rightarrow$  bound in Sobolev norms.

3D Jacobi-Anger gives the matrix  $\{M\}_{l,m;k} = Y_{l,m}(d_k)$  that depends on the choice of the directions.

Problem: an upper bound on  $||M^{-1}||$  is needed but M is not even always invertible!

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Solution:

- there exists an optimal choice s.t.  $\|M^{-1}\|_1 \leq 2\sqrt{\pi} p$ ;
- it corresponds to the extremal systems of Sloan and Womersley for quadrature on S<sup>2</sup>;
- some simple choices of points give good result, heuristic: d<sub>k</sub> have to be as "equispaced" as possible.

With this choice  $\rightarrow$  analogous results as in 2D.

## The final approximation by plane waves



Final estimate $\inf_{\alpha \in \mathbb{C}^p} \left\| u - \sum_{k=1}^p \alpha_k e^{i\omega x \cdot d_k} \right\|_{j,\omega,D} \le C h^{K+1-j} q^{-\lambda(K+1-j)} \|u\|_{K+1,\omega,D}$  $\ln 2D: \quad p = 2q+1, \quad \lambda(D) \quad \text{explicit}, \quad \forall \ d_k.$  $\ln 3D: \quad p = (q+1)^2, \quad \lambda(D) \quad \text{unknown, special } d_k.$ 

What we have proved:

- hp-estimates for circular/spherical and plane waves in 2D and 3D,
- all the constants are explicit in  $\omega h$ ,
- all the orders in *h* are sharp.

Open problems / work in progress:

explicit order of convergence in p in 3D convex domains,  $\bullet$ 

Vekua theory and approximation for Maxwell equation.

## Part IV

## Approximation for Maxwell equations

The vector field **u** is solution of Maxwell equations

 $\operatorname{curl}\operatorname{curl} \mathbf{u} - \omega^2 \mathbf{u} = \mathbf{0}$ 

if and only if

$$\begin{cases} -\Delta \mathbf{u}_j - \omega^2 \mathbf{u}_j = 0, \quad j = 1, 2, 3, \\ \operatorname{div} \mathbf{u} = 0. \end{cases}$$

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 $\begin{cases} p \text{ directions} \\ 3p \text{ plane waves} \end{cases} \xrightarrow{\text{same approximation as for Helmholtz,} \\ \text{non-Trefftz functions!} \end{cases}$ 

Basis of Maxwell plane wave functions:



Goal: prove convergence using 2p plane waves and preserving the Trefftz property.

### P.W. approximation: lazy approach

$$\begin{array}{l} \textbf{u} \text{ Maxwell} \quad \Rightarrow \quad \text{curl } \textbf{u} \text{ Maxwell} \quad \Rightarrow \quad \text{curl } \textbf{u} \text{ Helmoltz} \\ \\ \left\| \text{curl } \textbf{u} - \frac{\text{Helmholtz}}{\text{vector p.w.}} \right\|_{j,\omega,D} \leq C(hq^{-\lambda})^{K+1-j} \left\| \text{curl } \textbf{u} \right\|_{K+1,\omega,D} \end{array}$$

2 With  $j \ge 1$ , apply curl and reduce j (bad!):

not sharp!

### Vector S.H.: welcome to the jungle!

Two different orthogonal basis for  $\left(L^2(S^2)\right)^3$ :

$$\begin{cases} \mathbf{Y}_{l,m}(\mathbf{x}) = Y_{l,m}(\mathbf{x}) \; \frac{\mathbf{x}}{|\mathbf{x}|} \\ \mathbf{\Psi}_{l,m}(\mathbf{x}) = |\mathbf{x}| \; \nabla Y_{l,m}(\mathbf{x}) \\ \mathbf{\Phi}_{l,m}(\mathbf{x}) = \mathbf{x} \times \nabla Y_{l,m}(\mathbf{x}) \end{cases} \\ \begin{cases} \mathbf{I}_{l,m}(\mathbf{x}) = (l+1) \; \mathbf{Y}_{l+1,m}(\mathbf{x}) + \mathbf{\Psi}_{l+1,m}(\mathbf{x}) \\ \mathbf{T}_{l,m}(\mathbf{x}) = -\mathbf{\Phi}_{l,m}(\mathbf{x}) \\ \mathbf{N}_{l,m}(\mathbf{x}) = l \; \mathbf{Y}_{l-1,m}(\mathbf{x}) - \mathbf{\Psi}_{l-1,m}(\mathbf{x}) \end{cases} \end{cases}$$

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 $\mathbf{\Phi}_{l,m}, \mathbf{\Psi}_{l,m}$  tangential to  $S^2$ ,  $\mathbf{Y}_{l,m}$  orthogonal,

 $\mathbf{I}_{l,m}, \mathbf{T}_{l,m}, \mathbf{N}_{l,m}$  are traces of *l*-homogeneous harmonic vector polynomials.

Herglotz functions theory  $\rightarrow$  basis of Maxwell-GHPs:

$$\begin{cases} \mathbf{b}_{l,m}^{1}(\mathbf{x}) = j_{l}(\omega r) \, \mathbf{\Phi}_{l,m} \\ \mathbf{b}_{l,m}^{2}(\mathbf{x}) = \frac{l+1}{2l+1} \, j_{l-1}(\omega r) \, \mathbf{I}_{l-1,m} + \frac{l}{2l+1} \, j_{l+1}(\omega r) \, \mathbf{N}_{l+1,m}. \end{cases}$$

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In  $\mathbf{b}_{l,m}^2$  there are two Bessel functions of different indices:

 $\mathbf{V}_{2}[\mathbf{b}_{l,m}^{2}]$  is a non-homogeneous polynomial !

 $\rightarrow$  approximation theory is a bit more complicated.

## Approximation in *h* by Maxwell-GHPs

- (VERFÜRTH 1999) recursive definition of approximating polynomial P<sub>m,B</sub> on D: orders in h;
- for harmonic vector fields  $\mathbf{P}_{m,B}$  is the Taylor polynomial!
- approximate  $\mathbf{P}_{m,B}$  with  $\{\mathbf{V}_2[\mathbf{b}_{l,m}^1]\}_{l \leq L} \cup \{\mathbf{V}_2[\mathbf{b}_{l,m}^2]\}_{l \leq L+1}$ ;
- Vekua continuity  $\Rightarrow$  *h*-estimate for Maxwell solutions:

$$\left\|\mathbf{u} - \mathbf{Q}_{L}\right\|_{j,\omega,D} \leq C(\omega h) \ h^{L+1-j} \ \left\|\mathbf{u}\right\|_{L+1,\omega,D}$$

same order as Helmholtz, using a few more functions:

$$2(L+1)^2 - 2 + 2L + 3.$$

*p*-estimate impossible with this approach without any new ideas for the Helmholtz case.

#### Approximation in *h* by Maxwell plane waves

 $GHPs \leftrightarrow plane$  waves approximation relies on Jacobi-Anger exp.

We need a vector version of the Jacobi-Anger expansion that "preserves" Maxwell property:

$$e^{i\omega\mathbf{x}\cdot\mathbf{d}} \mathrm{Id} = 4\pi \sum_{l\geq 0} \sum_{|m|\leq l} i^l \left( \frac{1}{l(l+1)} \mathbf{b}_{l,m}^1(\omega\mathbf{x}) \,\overline{\mathbf{\Phi}_{l,m}(\mathbf{d})} - \frac{i}{l(l+1)} \,\mathbf{b}_{l,m}^2(\omega\mathbf{x}) \,\overline{\mathbf{\Psi}_{l,m}(\mathbf{d})} - i \,\mathbf{b}_{l,m}^\perp(\omega\mathbf{x}) \,\overline{\mathbf{\Psi}_{l,m}(\mathbf{d})} \right)$$

( $\mathbf{b}_{l,m}^{\perp}$  are the non-Maxwell vector GHPs).

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$$- \frac{i}{l(l+1)} \, \mathbf{b}_{l,m}^2(\omega\mathbf{x}) \,\overline{\mathbf{\Psi}_{l,m}(\mathbf{d})} \cdot \mathbf{A} - \underbrace{i \, \mathbf{b}_{l,m}^\perp(\omega\mathbf{x}) \,\overline{\mathbf{Y}_{l,m}(\mathbf{d})} \cdot \mathbf{A}}_{=0 \text{ if } \mathbf{d}\cdot\mathbf{A}=0}$$

( $\mathbf{b}_{l,m}^{\perp}$  are the non-Maxwell vector GHPs).

Maxwell PW = infinite linear combination of Maxwell GHPs.

Still some (technical ?) problems in the residual estimate to prove approximation in h.

## THANK YOU!