

Finite difference schemes for nonconservative hyperbolic systems

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- The hyperbolic conservation law

$$\mathbf{u}_t + \mathbf{f}(\mathbf{u})_x = 0 \quad (1)$$

$(\mathbf{u} : (a, b) \times [0, \infty) \rightarrow \mathbb{R}^m)$ has non-smooth solutions, and so must be interpreted in a weak, distributional manner:

$$\int_0^\infty \int_a^b \mathbf{u} \psi_t + \mathbf{f}(\mathbf{u}) \psi_x \, dx dt + \int_a^b \mathbf{u}(x, 0) \psi(x, 0) \, dx = 0$$

for all $\psi \in C_0^\infty((a, b) \times [0, \infty))$. To obtain uniqueness, *entropy conditions* must be added.

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- Entropy pair: $(\eta(\mathbf{u}), q(\mathbf{u}))$ with $\eta''(\mathbf{u}) > 0$ and $q'(\mathbf{u})^\top = \eta'(\mathbf{u})^\top \mathbf{f}'(\mathbf{u})$.

$$(\text{mpy. by } \eta'(\mathbf{u})^\top) \quad \Rightarrow \quad \eta(\mathbf{u})_t + q(\mathbf{u})_x = 0.$$

Entropy should be *dissipated* at shocks, giving the **entropy condition**

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(in the sense of distributions) for all entropy pairs (η, q) .

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- Have existence, uniqueness globally for scalar conservation laws and locally for systems.

- Can write (1) as $\mathbf{u}_t + \mathbf{f}'(\mathbf{u})\mathbf{u}_x = 0$. More generally:

$$\mathbf{w}_t + \mathbf{g}(\mathbf{w})\mathbf{w}_x = 0 \quad (2)$$

for some $\mathbf{g} \in C(\mathbb{R}^n; \mathbb{R}^{n \times n})$.

- $\mathbf{g}(\mathbf{w})\mathbf{w}_x$ for $\mathbf{w} \in BV((a, b) \times \mathbb{R}_+)$ is a *nonconservative product*.

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- (2) is *not* defined when \mathbf{w} is discontinuous – we cannot throw derivatives onto a test function ψ .
- **Example:** If H is the Heaviside function

$$H(x) = \begin{cases} 0 & \text{if } x < 0 \\ 1 & \text{if } x > 0 \end{cases}$$

then $\frac{dH}{dx} = \delta_0$, the Dirac measure, but

$$H \frac{dH}{dx} = H\delta_0$$

is undefined at 0.

DLM theory of nonconservative products

Fix $t \in \mathbb{R}_+$ and consider \mathbf{w} as a function in $BV((a, b); \mathbb{R}^n)$.

- Theory of Dal Maso, LeFloch and Murat [3]: Define $\mathbf{g}(\mathbf{w}) \frac{d\mathbf{w}}{dx}$ as a measure μ :
 - If \mathbf{w} is continuous in $B \subset (a, b)$ then

$$\mu(B) := \int_B \mathbf{g}(\mathbf{w}) \left(\frac{d\mathbf{w}}{dx} \right)$$

($\frac{d\mathbf{w}}{dx}$ is a Borel measure and $g(\mathbf{w})$ is continuous, so this is well-defined).

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- If \mathbf{w} is discontinuous at $x \in (a, b)$ then

$$\mu(\{x\}) := \int_0^1 \mathbf{g} \left(\phi(s; \mathbf{w}(x^-), \mathbf{w}(x^+)) \right) \frac{\partial \phi}{\partial s} (s; \mathbf{w}(x^-), \mathbf{w}(x^+)) ds$$

where $\phi : [0, 1] \times \mathbb{R}^n \times \mathbb{R}^n$ is a *family of paths*: for all $\mathbf{w}_L, \mathbf{w}_R, \mathbf{w} \in \mathbb{R}^n$ we have

$$\phi(0; \mathbf{w}_L, \mathbf{w}_R) = \mathbf{w}_L, \quad \phi(1; \mathbf{w}_L, \mathbf{w}_R) = \mathbf{w}_R, \quad \phi(s, \mathbf{w}, \mathbf{w}) \equiv \mathbf{w} \quad \forall s \in [0, 1].$$

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- We denote $\left[\mathbf{g}(\mathbf{w}) \frac{d\mathbf{w}}{dx} \right]_{\phi} = \mu$.
- **Theorem:** $\left[\mathbf{g}(\mathbf{w}) \frac{d\mathbf{w}}{dx} \right]_{\phi}$ is a bounded Borel measure.

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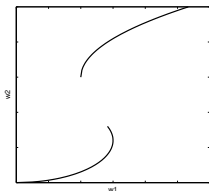
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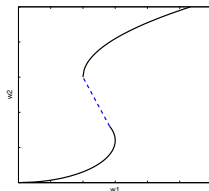
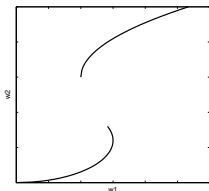
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Recall that a weak solution of (1) satisfies

$$\int_0^\infty \int_a^b \mathbf{u} \psi_t + \mathbf{f}(\mathbf{u}) \psi_x \, dx dt + \int_a^b \mathbf{u}(x, 0) \psi(x, 0) \, dx = 0$$

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Definition

A function $\mathbf{w} \in L^\infty([0, \infty); BV((a, b); \mathbb{R}^n))$ is a weak solution of (2) if

$$\int_0^\infty \int_a^b \mathbf{w} \psi_t \, dx - \langle [\mathbf{g}(\mathbf{w}(\cdot, t)) \mathbf{w}_x(\cdot, t)]_\phi, \psi(\cdot, t) \rangle dt + \int_a^b \mathbf{w}(x, 0) \psi(x, 0) \, dx = 0$$

for all $\psi \in C_0^\infty((a, b) \times [0, \infty))$.

Here, $\langle \cdot, \cdot \rangle$ denotes the pairing

$$\langle [\mathbf{g}(\mathbf{w}(\cdot, t)) \mathbf{w}_x(\cdot, t)]_\phi, \psi(\cdot, t) \rangle = \int_{(a, b)} \psi(x, t) [\mathbf{g}(\mathbf{w}(\cdot, t)) \mathbf{w}_x(\cdot, t)]_\phi(x),$$

where the integral is with respect to the measure $[\mathbf{g}(\mathbf{w}(\cdot, t)) \mathbf{w}_x(\cdot, t)]_\phi$.

- We discretize the domain into intervals $I_j = [x_{j-1/2}, x_{j+1/2}]$, with $x_{j+1/2} - x_{j-1/2} \equiv \Delta x$. We solve for

$$\mathbf{u}_j^n \approx \frac{1}{\Delta x} \int_{I_j} \mathbf{u}(x, t^n).$$

- A finite volume scheme for (1) is *conservative* if it is of the form

$$\mathbf{u}_j^{n+1} = \mathbf{u}_j^n - \frac{\Delta t}{\Delta x} (\mathbf{F}_{j+1/2} - \mathbf{F}_{j-1/2}),$$

where $\mathbf{F}_{j+1/2} = \mathbf{F}(\mathbf{u}_j^n, \mathbf{u}_{j+1}^n)$ satisfies $\mathbf{F}(\mathbf{u}, \mathbf{u}) = \mathbf{f}(\mathbf{u})$ for all $\mathbf{u} \in \mathbb{R}^n$.

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- A scheme for (2) is *path conservative with respect to ϕ* if it is of the form

$$\mathbf{w}_j^{n+1} = \mathbf{w}_j^n - \frac{\Delta t}{\Delta x} (\mathbf{D}_{j+1/2}^- + \mathbf{D}_{j-1/2}^+)$$

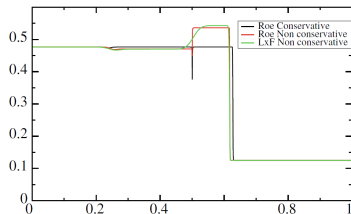
for some $\mathbf{D}_{j+1/2}^\pm = \mathbf{D}^\pm(\mathbf{w}_j^n, \mathbf{w}_{j+1}^n)$ which satisfies

- $\mathbf{D}^\pm(\mathbf{w}, \mathbf{w}) = 0$ for all $\mathbf{w} \in \mathbb{R}^n$
- $\mathbf{D}_{j+1/2}^- + \mathbf{D}_{j+1/2}^+ = \int_0^1 \mathbf{g}(\phi(s; \mathbf{w}_j, \mathbf{w}_{j+1})) \frac{\partial \phi}{\partial \mathbf{s}}(s; \mathbf{w}_j, \mathbf{w}_{j+1}) ds$.
- These two definitions are equivalent if $\mathbf{g}(\mathbf{u}) = \mathbf{f}'(\mathbf{u})$ for some \mathbf{f} .

- Pointwise convergence of numerical approximations \mathbf{w}^Δ to some \mathbf{w} does *not* imply that \mathbf{w} solves (2) (no Lax-Wendroff theorem).

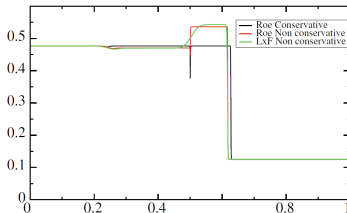
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Theorem (Castro et. al. [2])

Let $\mathbf{w}^{\Delta x}$ be computed by a path conservative scheme and assume that $\|\mathbf{w}^{\Delta x}(\cdot, t)\|_{\text{BV}} \leq C$ uniformly in time. If $\mathbf{w}^{\Delta x} \rightarrow \mathbf{w}$ pointwise a.e. as $\Delta x \rightarrow 0$, then

- (i) There is a bounded measure $\lambda : \mathbb{R} \times \mathbb{R}_+ \rightarrow \mathbb{R}^n$ such that

$$\mathbf{w}_t + [\mathbf{g}(\mathbf{w})\mathbf{w}_x]_\phi = \lambda.$$

- (ii) If the ϕ -graph completions of $\mathbf{w}^{\Delta x}$ converge uniformly to that of \mathbf{w} , then

$$\mathbf{w}_t + [\mathbf{g}(\mathbf{w})\mathbf{w}_x]_\phi = 0.$$

- Consider the model system

$$\begin{aligned}v_t - u_x &= 0 \\u_t + p_x &= 0 \\E_t + (pu)_x &= 0,\end{aligned}\tag{3}$$

with

$$E = e + \frac{u^2}{2}, \quad e = \frac{pv}{\gamma - 1}.$$

Here, v is specific volume, u velocity, p gas pressure, E total energy and e internal energy.

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- Abgrall and Karni [1] consider the equivalent, *nonconservative* system

$$\begin{aligned}v_t - u_x &= 0 \\u_t + p_x &= 0 \\e_t + pe_x &= 0.\end{aligned}\tag{4}$$

No path conservative schemes for (4) were found that converge to the entropy solution of (3) (the "correct" solution).

- Consider instead the following parabolic, regularized form of (3):

$$\begin{aligned}v_t - u_x &= \varepsilon v_{xx} \\u_t + p_x &= \varepsilon u_{xx} \\E_t + (\rho u)_x &= \varepsilon E_{xx}.\end{aligned}\tag{5}$$

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- The equivalent formulation in $\mathbf{w} = (v, u, e)$ is

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- We will discretize (5) and (6) using **entropy conservative** schemes for the left-hand sides and **central differences** for the right-hand sides.

- Entropy stable scheme for conservative system (5):

$$\begin{aligned} \frac{d}{dt} v_j - \frac{u_{j+1} - u_{j-1}}{2\Delta x} &= \varepsilon \frac{v_{j+1} - 2v_j + v_{j-1}}{\Delta x^2} \\ \frac{d}{dt} u_j + \frac{p_{j+1} - p_{j-1}}{2\Delta x} &= \varepsilon \frac{u_{j+1} - 2u_j + u_{j-1}}{\Delta x^2} \\ \frac{d}{dt} E_j + p_j \frac{u_{j+1} - u_{j-1}}{2\Delta x} + u_j \frac{p_{j+1} - p_{j-1}}{2\Delta x} &= \varepsilon \frac{E_{j+1} - 2E_j + E_{j-1}}{\Delta x^2} \end{aligned}$$

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- To avoid having to use very small Δx in order to resolve the viscous profile, we set

$$\varepsilon = \frac{c^n}{2} \Delta x,$$

where $c^n := \max_j |c_j^n|$ and c_j^n are the eigenvalues of $\mathbf{f}'(\mathbf{u}(x_j, t^n))$.

Let

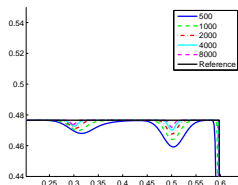
$$(v_0(x), u_0(x), p_0(x)) = \begin{cases} (8, 0, 0.1) & \text{if } x < 0.5 \\ (2.0984, 2.3047, 1) & \text{if } x > 0.5. \end{cases}$$

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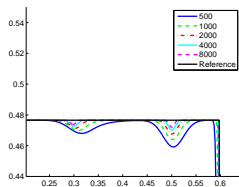


(a) Conservative approximation.

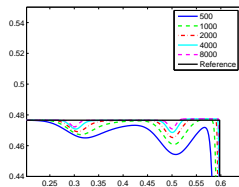
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(a) Conservative approximation.

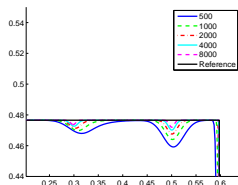


(b) Nonconservative approximation.

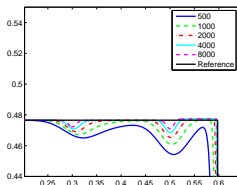
Let

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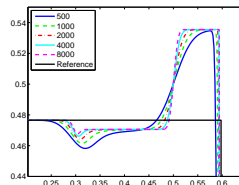
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(a) Conservative approximation.



(b) Nonconservative approximation.



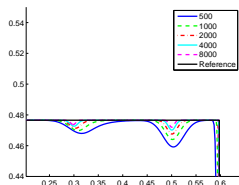
(c) Nonconservative approximation without u_x^2 term.

Numerical experiment

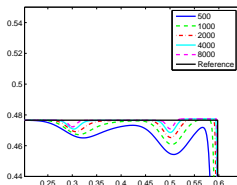
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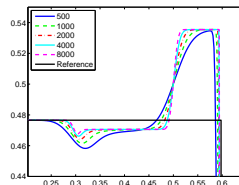
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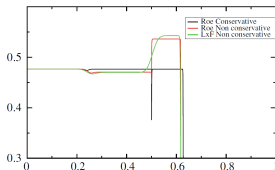
(a) Conservative approximation.



(b) Nonconservative approximation.



(c) Nonconservative approximation without u_x^2 term.



Consider the Isothermal Euler equations [4]

$$\begin{cases} \rho_t + (\rho u)_x = 0 \\ (\rho u)_t + (\rho u^2 + p)_x = 0, \end{cases} \quad \begin{cases} \rho_t + (\rho u)_x = 0 \\ u_t + \left(\frac{u^2}{2} + \log \rho \right)_x = 0. \end{cases} \quad (7)$$

We regularize these as

$$\begin{cases} \rho_t + (\rho u)_x = \varepsilon \rho_{xx} \\ (\rho u)_t + (\rho u^2 + p)_x = \varepsilon (\rho u)_{xx}, \end{cases} \quad \begin{cases} \rho_t + (\rho u)_x = \varepsilon \rho_{xx} \\ u_t + \left(\frac{u^2}{2} + \log \rho \right)_x = \varepsilon u_{xx} + 2\varepsilon (\log \rho)_x u_x. \end{cases} \quad (8)$$

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We discretize the regularized nonconservative system as before with **entropy conservative** schemes for the left-hand side and **central differences** for the right-hand side, obtaining

$$\begin{aligned} \frac{d}{dt} \rho_j + \frac{\rho_{j+1} u_{j+1} - \rho_{j-1} u_{j-1}}{2\Delta x} &= \varepsilon \frac{\rho_{j+1} - 2\rho_j + \rho_{j-1}}{\Delta x^2} \\ \frac{d}{dt} (\rho_j u_j) + \frac{u_{j+1}^2 - u_{j-1}^2}{4\Delta x} + \frac{\log \rho_{j+1} - \log \rho_{j-1}}{2\Delta x} &= \varepsilon \frac{u_{j+1} - 2u_j + u_{j-1}}{\Delta x^2} \\ &\quad + 2\varepsilon \left(\frac{\log \rho_{j+1} - \log \rho_{j-1}}{2\Delta x} \right) \left(\frac{u_{j+1} - u_{j-1}}{2\Delta x} \right) \end{aligned}$$

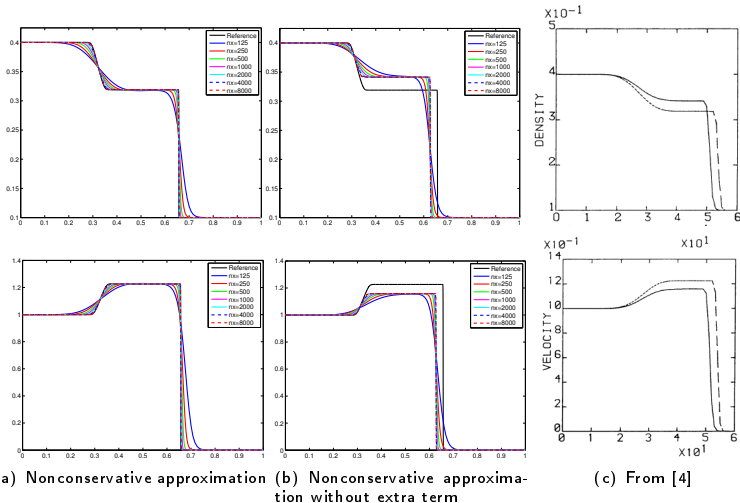
We consider the following numerical experiment, taken from [4]:

$$(\rho_0(x), u_0(x)) = \begin{cases} (0.4, 1) & \text{if } x < 0.5 \\ (0.1, 0) & \text{if } x > 0.5. \end{cases}$$

Numerical experiment

We consider the following numerical experiment, taken from [4]:

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- Nonconservative systems are highly sensitive to regularization terms.
- Path conservative schemes may converge to incorrect regularization limits. (Equivalent equation has non-vanishing source term.)
- A faithful discretization of physical diffusive terms is vital for convergence.
- The recipe of entropy conservative flux + discretization of physical diffusion shows promise.



R. Abgrall and S. Karni.

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