

Space-time sparse discretization of linear parabolic equations

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Introduction

Let $V \hookrightarrow H \cong H' \hookrightarrow V'$ be a Gelfand triple of separable Hilbert spaces. Consider the abstract parabolic equation in $t \in J \subset \mathbb{R}$

$$\partial_t u + Au = g, \quad u(0) = h \in H \quad (\text{PDE})$$

where

- ▶ $g : J \rightarrow V'$
- ▶ $A : J \rightarrow \mathcal{L}(V, V')$
- ▶ $u : J \rightarrow V$

(PDE) models

- ▶ heat conduction, e.g.

$$H_0^1(D) = V \hookrightarrow H = L^2(D) \cong H' \hookrightarrow V' = H^{-1}(D)$$

- ▶ option pricing, etc

Introduction

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- ▶ $g : J \rightarrow V'$
- ▶ $A : J \rightarrow \mathcal{L}(V, V')$
- ▶ $u : J \rightarrow V$

(PDE) models

- ▶ parametric heat conduction, e.g.

$$L^2_\pi(U, H^1_0(D)) \hookrightarrow L^2_\pi(U, L^2(D)) \hookrightarrow L^2_\pi(U, H^{-1}(D))$$

- ▶ option pricing, etc

Introduction

Numerical solution of (PDE)

- ▶ many (adaptive, multi-level) Galerkin methods exist
- ▶ essentially variations on the “method of lines”

Issues

- ▶ compression of u as a function of “space-time”
- ▶ efficient algorithms for computing the *compressed* u
- ▶ provable error and complexity bounds
- ▶ **design of stable finite element spaces***

* does not arise in the adaptive wavelet method [SS09]

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References I

hp-dG and -cG time-stepping

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Truly space-time wavelet methods

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- [SS09] Christoph Schwab and Rob Stevenson, “Space-time adaptive wavelet methods for parabolic evolution problems”, Mathematics of Computation, 78, no. 267, 1293–1318, **2009**
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Introduction – continued

Class of stable FE spaces: key steps

- ▶ variational formulation of (PDE) in space-time
- ▶ test space suitably finer than ansatz space (**generic**)
- ▶ anisotropic (tensor product) wavelets in space-time
- ▶ **sparse** tensor product spaces in space-time
- ▶ derivation of a non-square (overdetermined) linear system
- ▶ corresponding normal equations are well-conditioned
- ▶ iterative solution (= residual minimization)

Variational formulation

The variational formulation, based on the bilinear form

$$b : \underbrace{L^2(J; V) \cap H^1(J; V')}_{\mathcal{U}} \times \underbrace{L^2(J; V) \times H}_{\mathcal{V}=\mathcal{V}_1 \times \mathcal{V}_2} \rightarrow \mathbb{R},$$

$$b(u, v) = \int_J \langle \partial_t u + Au, v_1 \rangle_{V' \times V} dt + \langle u(0), v_2 \rangle_H$$

and the linear functional

$$f : \underbrace{L^2(J; V) \times H}_{\mathcal{V}=\mathcal{V}_1 \times \mathcal{V}_2} \rightarrow \mathbb{R}, \quad f(v) = \int_J \langle g, v_1 \rangle_{V' \times V} dt + \langle h, v_2 \rangle_H,$$

reads: find $u \in \mathcal{U}$ s.t.

$$b(u, v) = f(v) \quad \forall v \in \mathcal{V}.$$

Variational formulation

Assume $\exists \alpha > 0, \mathbf{c} \in \mathbb{R}$ s.t. $\forall \zeta, \eta \in V$:

- ▶ $\sup_{t \in J} \|A(t)\|_{\mathcal{L}(V, V')} < \infty$
- ▶ $J \ni t \mapsto \langle A(t)\zeta, \eta \rangle_{V' \times V}$ measurable
- ▶ $\langle A(t)\eta, \eta \rangle_{V' \times V} + \mathbf{c} \|\eta\|_H^2 \geq \alpha \|\eta\|_V^2$ for all $t \in J$

and

- ▶ $g \in L^2(J; V')$
- ▶ $h \in H$.

Then “ $b(u, \cdot) = f(\cdot)$ ” is well-posed [SS09]. In particular,

$$\inf_{u \in \mathcal{U} \setminus \{0\}} \sup_{v \in \mathcal{V} \setminus \{0\}} \frac{b(u, v)}{\|u\|_{\mathcal{U}} \|v\|_{\mathcal{V}}} > 0.$$

Below assume: $\mathbf{c} = 0$ and $A = A'$ but not $A^{-1}(t) \in K(V', V)$

Abstract stability result

Theorem

Let $\mathcal{R} \subseteq \mathcal{U}$ and $\mathcal{S} = \mathcal{S}_1 \times \mathcal{S}_2 \subseteq \mathcal{V}_1 \times \mathcal{V}_2 = \mathcal{V}$ be subspaces.

Assume

- ▶ there exists $\mathcal{K}(\mathcal{S}_1) > 0$ such that

$$\forall \mathbf{z}' \in \mathcal{S}_1 : \|\mathbf{z}'\|_{\mathcal{S}_1'} := \sup_{\mathbf{z} \in \mathcal{S}_1 \setminus \{0\}} \frac{\langle \mathbf{z}', \mathbf{z} \rangle_{\mathcal{V}_1' \times \mathcal{V}_1}}{\|\mathbf{z}\|_{\mathcal{V}_1}} \geq \mathcal{K}(\mathcal{S}_1) \|\mathbf{z}'\|_{\mathcal{V}_1'}$$

- ▶ $\mathcal{R} \subseteq \mathcal{S}_1$ and $\partial_t \mathcal{R} \subseteq \mathcal{S}_1$
- ▶ $\mathcal{R}|_{t=0} = \{u(t=0) \in H : u \in \mathcal{R}\} \subseteq \mathcal{S}_2$

Then: $\exists \gamma > 0$, only dependent on $\mathcal{K}(\mathcal{S}_1)$ and A , such that

$$\inf_{u \in \mathcal{R} \setminus \{0\}} \sup_{v \in \mathcal{S} \setminus \{0\}} \frac{b(u, v)}{\|u\|_{\mathcal{U}} \|v\|_{\mathcal{V}}} \geq \gamma > 0.$$

Abstract stability result

Btw:

$$\forall \mathbf{z}' \in \mathcal{S}_1 : |\mathbf{z}'|_{\mathcal{S}'_1} := \sup_{\mathbf{z} \in \mathcal{S}_1 \setminus \{0\}} \frac{\langle \mathbf{z}', \mathbf{z} \rangle_{\mathcal{V}'_1 \times \mathcal{V}_1}}{\|\mathbf{z}\|_{\mathcal{V}_1}} \geq \mathcal{K}(\mathcal{S}_1) \|\mathbf{z}'\|_{\mathcal{V}'_1}$$

is equivalent to

$$\inf_{\mathbf{z}' \in \mathcal{S}_1 \setminus \{0\}} \sup_{\mathbf{z} \in \mathcal{S}_1 \setminus \{0\}} \frac{\langle \mathbf{z}', \mathbf{z} \rangle_{\mathcal{V}'_1 \times \mathcal{V}_1}}{\|\mathbf{z}'\|_{\mathcal{V}'_1} \|\mathbf{z}\|_{\mathcal{V}_1}} \geq \mathcal{K}(\mathcal{S}_1)$$

Abstract stability result

Proof, step I

- ▶ Let $u \in \mathcal{R}$.
- ▶ Set $\mathcal{Z} := \mathcal{V}_1 = L^2(J; V)$ with $\|\cdot\|_{\mathcal{Z}} = \langle \cdot, \cdot \rangle_{\mathcal{Z}}^{1/2}$,

$$\langle z, \tilde{z} \rangle_{\mathcal{Z}} = \int_J \langle Az, \tilde{z} \rangle_{V' \times V} \quad \forall z, \tilde{z} \in \mathcal{Z}.$$

Note: $\|\cdot\|_{\mathcal{Z}} \sim \|\cdot\|_{L^2(J; V)} =: \|\cdot\|_{\mathcal{V}_1}$ and $u \in \mathcal{R} \subseteq \mathcal{S}_1 \subseteq \mathcal{Z}$.

- ▶ Define $v_2 := u(0) \in H$ and $v_1 \in \mathcal{S}_1$ by

$$\langle v_1, \tilde{v}_1 \rangle_{\mathcal{Z}} = \int_J \langle \partial_t u + Au, \tilde{v}_1 \rangle_{V' \times V} \quad \forall \tilde{v}_1 \in \mathcal{S}_1.$$

Abstract stability result

Proof, step II

- ▶ choosing $\tilde{v}_1 = v_1$ yields fact 1

$$\begin{aligned} b(u, (v_1, v_2)) &= \int_J \langle \partial_t u + Au, v_1 \rangle_{V' \times V} + \langle u(0), v_2 \rangle_H \\ &= \langle v_1, v_1 \rangle_{\mathcal{Z}} + \langle u(0), v_2 \rangle_H \\ &= \|v_1\|_{\mathcal{Z}}^2 + \|v_2\|_{V_2}^2 \end{aligned}$$

- ▶ choosing $\tilde{v}_1 = u$ yields fact 2

$$\begin{aligned} \langle v_1, u \rangle_{\mathcal{Z}} &= \int_J \langle \partial_t u + Au, u \rangle_{V' \times V} \\ &= \int_J \langle Au, u \rangle_{V' \times V} + \int_J \langle \partial_t u, u \rangle_{V' \times V} \\ &= \|u\|_{\mathcal{Z}}^2 + \frac{1}{2} \left(\|u(T)\|_H^2 - \|u(0)\|_H^2 \right) \end{aligned}$$

Abstract stability result

Proof, step III

Using $\partial_t u \in \partial_t \mathcal{R} \subseteq \mathcal{S}_1$ we obtain fact 3

$$\begin{aligned} \mathcal{K}(\mathcal{S}_1) \|\partial_t u\|_{\mathcal{V}'_1} &\leq |\partial_t u|_{\mathcal{S}'_1} = \sup_{\tilde{v}_1 \in \mathcal{S}_1 \setminus \{0\}} \frac{\langle \partial_t u, \tilde{v}_1 \rangle_{\mathcal{V}'_1 \times \mathcal{V}_1}}{\|\tilde{v}_1\|_{\mathcal{V}_1}} \\ &= \sup_{\tilde{v}_1 \in \mathcal{S}_1 \setminus \{0\}} \frac{\int_J \langle \partial_t u + Au - Au, \tilde{v}_1 \rangle_{V' \times V}}{\|\tilde{v}_1\|_{\mathcal{V}_1}} \\ &= \sup_{\tilde{v}_1 \in \mathcal{S}_1 \setminus \{0\}} \frac{\langle v_1, \tilde{v}_1 \rangle_{\mathcal{Z}} - \langle u, \tilde{v}_1 \rangle_{\mathcal{Z}}}{\|\tilde{v}_1\|_{\mathcal{V}_1}} \\ &= \sup_{\tilde{v}_1 \in \mathcal{S}_1 \setminus \{0\}} \frac{\langle v_1 - u, \tilde{v}_1 \rangle_{\mathcal{Z}}}{\|\tilde{v}_1\|_{\mathcal{Z}}} \frac{\|\tilde{v}_1\|_{\mathcal{Z}}}{\|\tilde{v}_1\|_{\mathcal{V}_1}} \\ &\leq \|v_1 - u\|_{\mathcal{Z}} \|\text{Id}\|_{\mathcal{L}(\mathcal{V}_1, \mathcal{Z})} \end{aligned}$$

with $\|\text{Id}\|_{\mathcal{L}(\mathcal{V}_1, \mathcal{Z})} = \text{ess sup}_{t \in J} \|A(t)\|_{\mathcal{L}(V, V')}^{1/2}$.

Abstract stability result

Proof, wrap up

We obtain

$$\begin{aligned} b(u, (v_1, v_2)) &\stackrel{1}{=} \|v_1\|_{\mathcal{Z}}^2 + \|v_2\|_{\mathcal{V}_2}^2 \geq \|v_1\|_{\mathcal{Z}}^2 + \|u(0)\|_H^2 - \|u(T)\|_H^2 \\ &\stackrel{2}{=} \|v_1 - u\|_{\mathcal{Z}}^2 + \|u\|_{\mathcal{Z}}^2 \\ &\stackrel{3}{\geq} \tilde{\gamma}^2 \left(\|\partial_t u\|_{\mathcal{V}'_1}^2 + \|u\|_{\mathcal{Z}}^2 \right) \end{aligned}$$

with $\tilde{\gamma} = \min\{\mathcal{K}(\mathcal{S}_1) \|\text{Id}\|_{\mathcal{L}(\mathcal{V}_1, \mathcal{Z})}^{-1}, 1\}$, and thus

$$\begin{aligned} b(u, (v_1, v_2)) &\geq \tilde{\gamma} \sqrt{\|\partial_t u\|_{L^2(\mathcal{J}; \mathcal{V}'_1)}^2 + \|u\|_{\mathcal{Z}}^2} \sqrt{\|v_1\|_{\mathcal{Z}}^2 + \|v_2\|_{\mathcal{V}_2}^2} \\ &\geq \gamma \|u\|_{L^2(\mathcal{J}; \mathcal{V}) \cap H^1(\mathcal{J}; \mathcal{V}'_1)} \|(v_1, v_2)\|_{L^2(\mathcal{J}; \mathcal{V}) \times H} \end{aligned}$$

with $\gamma \sim \tilde{\gamma}$.

Abstract stability result

Assumptions on $\mathcal{R} \subseteq \mathcal{U}$ and $\mathcal{S} = \mathcal{S}_1 \times \mathcal{S}_2 \subseteq \mathcal{V}_1 \times \mathcal{V}_2 = \mathcal{V}$

- ▶ there exists $\mathcal{K}(\mathcal{S}_1) > 0$ such that

$$\inf_{z' \in \mathcal{S}_1 \setminus \{0\}} \sup_{z \in \mathcal{S}_1 \setminus \{0\}} \frac{\langle z', z \rangle_{\mathcal{V}_1 \times \mathcal{V}_1}}{\|z'\|_{\mathcal{V}_1} \|z\|_{\mathcal{V}_1}} \geq \mathcal{K}(\mathcal{S}_1)$$

- ▶ $\mathcal{R} \subseteq \mathcal{S}_1$ and $\partial_t \mathcal{R} \subseteq \mathcal{S}_1$
- ▶ $\mathcal{R}|_{t=0} = \{u(t=0) \in H : u \in \mathcal{R}\} \subseteq \mathcal{S}_2$

can be relaxed (numerics below).

On condition $\mathcal{K}(\mathcal{S}_1) > 0$

Lemma

Assume

- ▶ $\mathcal{S}_1 \subseteq V$ satisfies

$$\inf_{s' \in \mathcal{S}_1 \setminus \{0\}} \sup_{s \in \mathcal{S}_1 \setminus \{0\}} \frac{\langle s', s \rangle_{V' \times V}}{\|s'\|_{V'} \|s\|_V} \geq \kappa(\mathcal{S}_1) > 0$$

- ▶ similarly $\kappa(\tilde{\mathcal{S}}_1) > 0$ for $\tilde{\mathcal{S}}_1 \subseteq V$
- ▶ subspaces $E, \tilde{E} \subseteq L^2(J)$ are orthogonal in $L^2(J)$

Then $\mathcal{S}_1 := (E \otimes \mathcal{S}_1) + (\tilde{E} \otimes \tilde{\mathcal{S}}_1) \subseteq L^2(J; V)$ satisfies

$$\mathcal{K}(\mathcal{S}_1) \geq \inf\{\kappa(\mathcal{S}_1), \kappa(\tilde{\mathcal{S}}_1)\} > 0.$$

Note: generalizes to $E, \tilde{E}, \dots \subseteq L^2(J)$.

On condition $\mathcal{K}(\mathcal{S}_1) > 0$

Proof of Lemma: $\dim E = \dim \tilde{E} = 1$

Let $v \in \mathcal{S}$ and $\tilde{v} \in \tilde{\mathcal{S}}$ (subscripts omitted). Let $E = \text{span}\{e\}$ and $\tilde{E} = \text{span}\{\tilde{e}\}$, $v = e \otimes s$ and $\tilde{v} = \tilde{e} \otimes \tilde{s}$. By assumption, $\exists s' \in \mathcal{S}$:

- ▶ $\kappa(\mathcal{S}) \|s'\|_{\mathcal{V}'} \|s\|_{\mathcal{V}} \leq \langle s', s \rangle_{\mathcal{V}' \times \mathcal{V}}$
- ▶ w.l.o.g. $\|s'\|_{\mathcal{V}'} = \|s\|_{\mathcal{V}}$

and similarly for some $\tilde{s}' \in \tilde{\mathcal{S}}$. Therefore, $v' := e \otimes s'$ and $\tilde{v}' := \tilde{e} \otimes \tilde{s}'$ are orthogonal in \mathcal{V} and \mathcal{V}' , and moreover

$$\begin{aligned} \|v' + \tilde{v}'\|_{\mathcal{V}'} \|v + \tilde{v}\|_{\mathcal{V}} &= \sqrt{\|v'\|_{\mathcal{V}'}^2 + \|\tilde{v}'\|_{\mathcal{V}'}^2} \sqrt{\|v\|_{\mathcal{V}}^2 + \|\tilde{v}\|_{\mathcal{V}}^2} \\ &= \sqrt{\|s'\|_{\mathcal{V}'}^2 + \|\tilde{s}'\|_{\mathcal{V}'}^2} \sqrt{\|s\|_{\mathcal{V}}^2 + \|\tilde{s}\|_{\mathcal{V}}^2} \\ &= \|s'\|_{\mathcal{V}'} \|s\|_{\mathcal{V}} + \|\tilde{s}'\|_{\mathcal{V}'} \|\tilde{s}\|_{\mathcal{V}} \\ &\leq \kappa(\mathcal{S})^{-1} \langle v', v \rangle_{\mathcal{V}' \times \mathcal{V}} + \kappa(\tilde{\mathcal{S}})^{-1} \langle \tilde{v}', \tilde{v} \rangle_{\mathcal{V}' \times \mathcal{V}} \\ &\leq \max\{\kappa(\mathcal{S})^{-1}, \kappa(\tilde{\mathcal{S}})^{-1}\} \langle v' + \tilde{v}', v + \tilde{v} \rangle_{\mathcal{V}' \times \mathcal{V}} \end{aligned}$$

On condition $\mathcal{K}(\mathcal{S}_1) > 0$

Application of Lemma

Assume

- ▶ closed subspaces $E^{(0)} \subseteq E^{(1)} \subseteq \dots \subseteq L^2(J)$
- ▶ closed subspaces $\mathcal{S}_1^{(0)} \subseteq \mathcal{S}_1^{(1)} \subseteq \dots \subseteq V$
- ▶ $\kappa(\mathcal{S}_1^{(\ell)}) \geq \kappa > 0$ for all $\ell \geq 0$.

Then for each $L \geq 0$ there holds

$$\mathcal{K} \left(\sum_{\ell=0}^L E^{(\ell)} \otimes \mathcal{S}_1^{(L-\ell)} \right) \geq \kappa > 0.$$

Proof: using $F^{(\ell)} := (E^{(\ell-1)})^{\perp L^2(J)} \cap E^{(\ell)}$, $\ell \geq 1$ and $F^{(0)} := E^{(0)}$,

$$\sum_{\ell=0}^L E^{(\ell)} \otimes \mathcal{S}_1^{(L-\ell)} = \sum_{\ell=0}^L \left(E^{(\ell-1)} + F^{(\ell)} \right) \otimes \mathcal{S}_1^{(L-\ell)} = \sum_{\ell=0}^L F^{(\ell)} \otimes \mathcal{S}_1^{(L-\ell)}.$$

Example

List of symbols

- ▶ Time interval $J = (0, T) \subset\subset \mathbb{R}$
- ▶ Open Lipschitz domain $D \subset\subset \mathbb{R}^d$, $d \geq 1$
- ▶ $H_0^1(D) = V \hookrightarrow H = L^2(D) \cong H' \hookrightarrow V' = H^{-1}(D)$
- ▶ Initial datum $h \in L^2(D)$
- ▶ Source term $g \in L^2(J, H^{-1}(D))$
- ▶ Conductivity $q \in L^\infty(D \times J)$ uniformly positive,

$$0 < a_{\min} \leq \operatorname{ess\,inf}_{D \times J} q \leq \operatorname{ess\,sup}_{D \times J} q \leq a_{\max} < \infty$$

Example

(PDE) in strong form

Find $u : D \times J \rightarrow \mathbb{R}$ such that

$$\partial_t u(\mathbf{x}, t) - \nabla \cdot (q(\mathbf{x}, t) \nabla u(\mathbf{x}, t)) = g(\mathbf{x}, t), \quad (\mathbf{x}, t) \in D \times J$$

with initial condition

$$u(\mathbf{x}, 0) = h(\mathbf{x}), \quad \mathbf{x} \in D$$

and boundary condition

$$u(\mathbf{x}, t) = 0, \quad (\mathbf{x}, t) \in \partial D \times J$$

Example

(PDE) in weak form

Find $u \in \mathcal{U} = L^2(J, H_0^1(D)) \cap H^1(J, H^{-1}(D))$ such that

$$\int_J \int_D (v_1 \partial_t u + q \nabla u \cdot \nabla v_1) \, dx dt = \int_J \int_D g v_1 \, dx dt$$

and

$$\int_D u(0) v_2 \, dx = \int_D h v_2 \, dx$$

for all $v = (v_1, v_2) \in \mathcal{V} = L^2(J, H_0^1(D)) \times L^2(D)$,
where q, u, v_1, g depend on (x, t) , and $u(0), h, v_2$ on x

Example

(PDE) in weak form

With bilin. form $b : \mathcal{U} \times \mathcal{V} \rightarrow \mathbb{R}$ and lin. functional $f : \mathcal{V} \rightarrow \mathbb{R}$,

$$b(u, v) = \int_J \int_D (v_1 \partial_t u + q \nabla u \cdot \nabla v_1) dx dt + \int_D u(0) v_2 dx$$

and

$$f(v) = \int_J \int_D g v_1 dx dt + \int_D h v_2 dx,$$

the variational formulation reads: find

$$u \in \mathcal{U} : \quad b(u, v) = f(v) \quad \forall v \in \mathcal{V}$$

Example

Choice of temporal basis

Let $\Theta_L = \{\theta_\lambda : \lambda \in \mathcal{I}_\Theta : |\lambda| \leq L\} \subset L^2(J)$ be

- ▶ a Riesz basis for its span uniformly in level $L \geq 0$:

$$\|\Theta_L^\top \mathbf{c}\|_{L^2(J)} \sim \|\mathbf{c}\|_2 \quad \forall \mathbf{c} \in \mathbb{R}^{\#\Theta_L}$$

- ▶ defined w.r.t. an equidistant partition of $J = (0, T)$ with width $h \sim 2^{-L}$
- ▶ piecewise linear continuous
- ▶ s.t. $\bigcup_{\ell \geq 0} \Theta_\ell$ rescales to a Riesz basis for $H^1(J)$

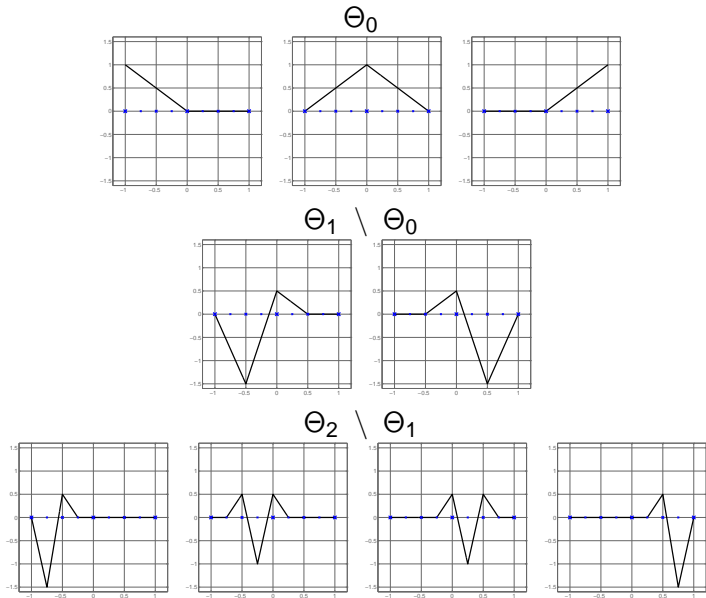


Figure: Piecewise linear continuous biorthogonal B-spline wavelets

Example

Choice of spatial basis

Let $\Sigma_L = \{\sigma_\mu : \mu \in \mathcal{I}_\Sigma : |\mu| \leq L\} \subset L^2(D)$ be

- ▶ a Riesz basis for its span uniformly in level $L \geq 0$
- ▶ defined w.r.t. a sequence of quasi-uniform nested triangulations of $D \subset \mathbb{R}^d$ with mesh width $h \sim 2^{-L}$
- ▶ s.t. $\bigcup_{\ell \geq 0} \Sigma_\ell$ rescales to a Riesz basis for $H_0^1(D)$
- ▶ (s.t. $\bigcup_{\ell \geq 0} \Sigma_\ell$ rescales to a Riesz basis for $H^{-1}(D)$)

Example

Choice of ansatz/test spaces I

Define **full** tensor product

- ▶ ansatz space $R_L \subset \mathcal{U}$ spanned by

$$\{\theta_\lambda \otimes \sigma_\mu : |\lambda| \leq L, |\mu| \leq \rho L\}$$

- ▶ test space $S_L \subset \mathcal{V}$ spanned by

$$\{\theta_\lambda \otimes \sigma_\mu : |\lambda| \leq L + 1, |\mu| \leq \rho L\} \times \{\sigma_\mu : |\mu| \leq \rho L\}$$

where $\rho > 0$ is the degree of anisotropy in the refinement

Example

Choice of ansatz/test spaces II

Define **sparse** tensor product

- ▶ ansatz space $R_L \subset \mathcal{U}$ spanned by

$$\{\theta_\lambda \otimes \sigma_\mu : |\lambda| + \rho^{-1}|\mu| \leq L\}$$

- ▶ test space $S_L \subset \mathcal{V}$ spanned by

$$\{\theta_\lambda \otimes \sigma_\mu : \min\{|\lambda| - 1, 0\} + \rho^{-1}|\mu| \leq L\} \times \{\sigma_\mu : |\mu| \leq \rho L\}$$

where $\rho > 0$ is the degree of anisotropy in the refinement

Example

Formulation via residual minimization (FTP case)

The discrete version of the variational formulation: find

$$\tilde{u}_L := \arg \min_{w \in R_L} \max_{v \in S_L \setminus \{0\}} \frac{|b(w, v) - f(v)|}{\|v\|_V}$$

motivates, via Riesz bases $\bigcup_{\ell \geq 0} \Theta_\ell$ and $\bigcup_{\ell \geq 0} \Sigma_\ell$, the definition

$$\mathbf{u}_L := \arg \min_{\mathbf{w} \in \mathbb{R}^{\dim R_L}} \|\mathbf{B}_L \mathbf{w} - \mathbf{f}_L\|_2 \quad (\text{argmin})$$

which defines $u_L = [\Theta_L \otimes \Sigma_L]^\top \mathbf{u}_L \in R_L$. In general $u_L \neq \tilde{u}_L$.

Example

Formulation via residual minimization (FTP case)

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which defines $u_L = [\Theta_L \otimes \Sigma_L]^T \mathbf{u}_L \in R_L$. In general $u_L \neq \tilde{u}_L$.

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which defines $u_L = [\Theta_L \otimes \Sigma_L]^T \mathbf{u}_L \in R_L$. In general $u_L \neq \tilde{u}_L$.

Example

Quasi-optimality

Theorem

The least-squares Galerkin solution u_L exists, is unique and converges quasi-optimally uniformly in $L \geq 0$: there exists $C > 0$ such that $\forall L \geq 0$

$$\|u_L - u\|_{\mathcal{U}} \leq C \inf_{w_L \in R_L} \|w_L - u\|_{\mathcal{U}}.$$

Example

Numerics I – smooth solution, FTP

Experimental set-up

- ▶ $D = (-1, 1) \subset \mathbb{R}$, $J = (0, T)$ with $T = 2$
- ▶ conductivity in (PDE) is $q \equiv 1$
- ▶ exact solution

$$u(x, t) = e^{-t} \cos \frac{x\pi}{2}, \quad (x, t) \in D \times J,$$

- ▶ piecewise linear continuous B-spline wavelet basis
- ▶ degree of anisotropy in refinement $\rho = 1$

Example

Numerics I – smooth solution, FTP

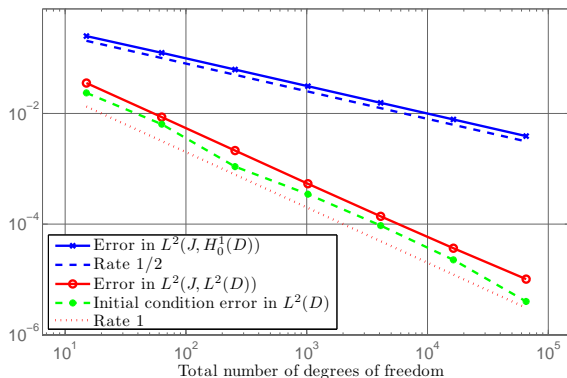


Figure: Convergence of the Galerkin solution u_L to a smooth u

Example

Numerics I – smooth solution, FTP

The system (argmin) is

- ▶ sparse
- ▶ well-conditioned

which suggests the use of an iterative least squares algorithm¹

Level L	1	2	...	5	6	7
ndof + 1	2^4	2^6	...	2^{12}	2^{14}	2^{16}
# iterations	11	41	...	315	442	574
\log_{10} rel. res.	-1.51	-2.08	...	-3.54	-4.02	-4.5

Table: The number of MATLAB's `lsqr` iterations with tolerance 10^{-10} , the corresponding number of degrees of freedom, and the relative residual on various discretization levels L for u_L

¹Paige and Saunders, SIAM J. Numer. Anal, 12, **1975** 

Example

Numerics II – rough solution, FTP

Experimental set-up

- ▶ $D = (-1, 1) \subset \mathbb{R}$, $J = (0, T)$ with $T = 2$
- ▶ source $g \equiv 1$, initial condition $h \equiv 0$
- ▶ conductivity in (PDE) is $q(x, t) = 1 - \frac{1}{2} \text{sign}(2 + x - 2t)$
- ▶ piecewise linear continuous B-spline wavelet basis
- ▶ degree of anisotropy in refinement $\rho = 1$
- ▶ reference solution on level $L = 7$

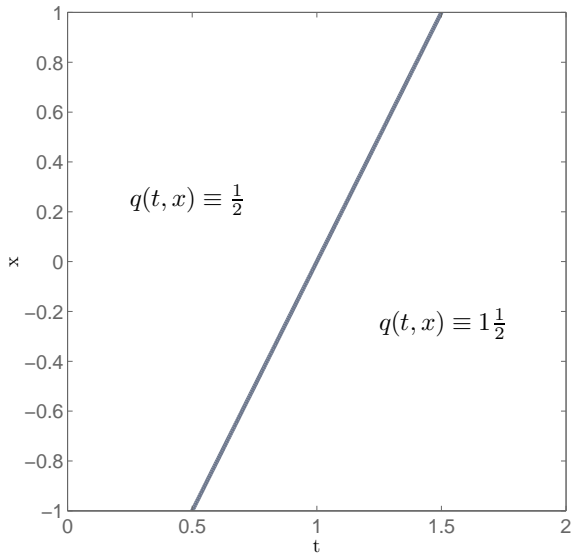


Figure: Conductivity q

Example

Numerics II – rough solution, FTP

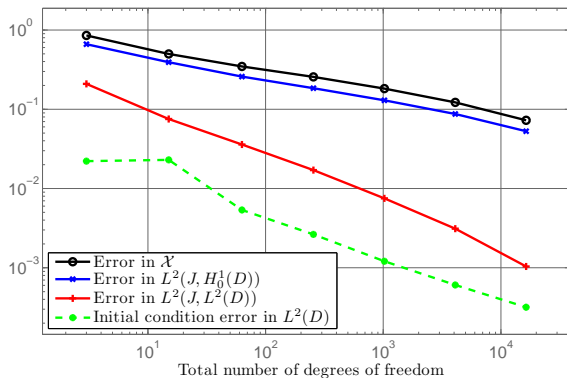


Figure: Convergence² of the Galerkin solution u_L to u_7

² $\mathcal{X} \equiv \mathcal{U}$

Example

Numerics III – FTP vs STP

Experimental set-up

- ▶ $D = (-1, 1) \subset \mathbb{R}$, $J = (0, T)$ with $T = 2$
- ▶ conductivity $q \equiv 1$, initial condition $h \equiv 0$
- ▶ source $g(x, t) = \cos(x + \cos \frac{\pi t}{2}) \sin^2 \frac{\pi t}{2}$
- ▶ piecewise linear continuous B-spline wavelet basis
- ▶ degree of anisotropy in refinement $\rho = 1$
- ▶ reference FTP solution on level $L = 7$

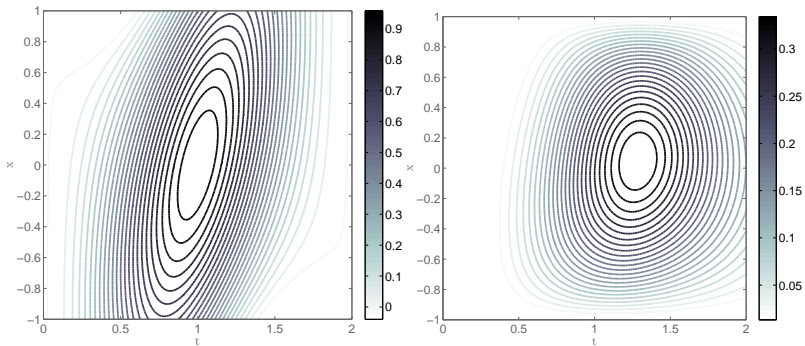


Figure: Source g (left) and solution u (right)

Example

Numerics III – FTP vs STP

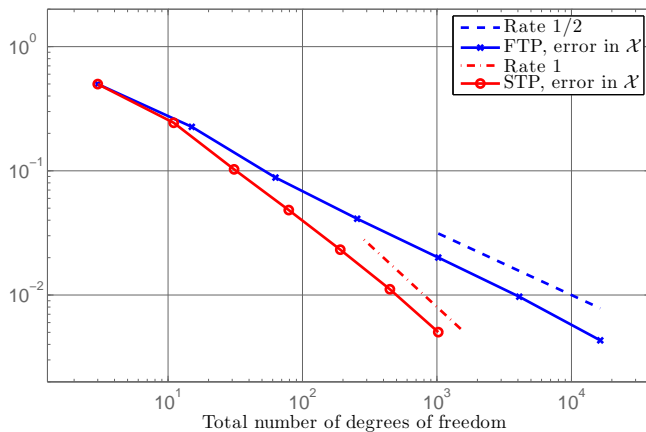


Figure: Convergence³ of the Galerkin solution: STP vs FTP

³ $\mathcal{X} \equiv \mathcal{U}$

Outro

Review

- ▶ sparse tensor formulation of (PDE) in space-time
- ▶ inf-sup condition for the associated bilinear form
- ▶ quasi-optimality of the Galerkin least squares solution
- ▶ examples

In progress

- ▶ sparse discretization of parametric parabolic equations
- ▶ weighted spaces for corners of the space-time cylinder

Thank You!